

Buck Converter Stability checks using Richtek Fast Load Transient Tool

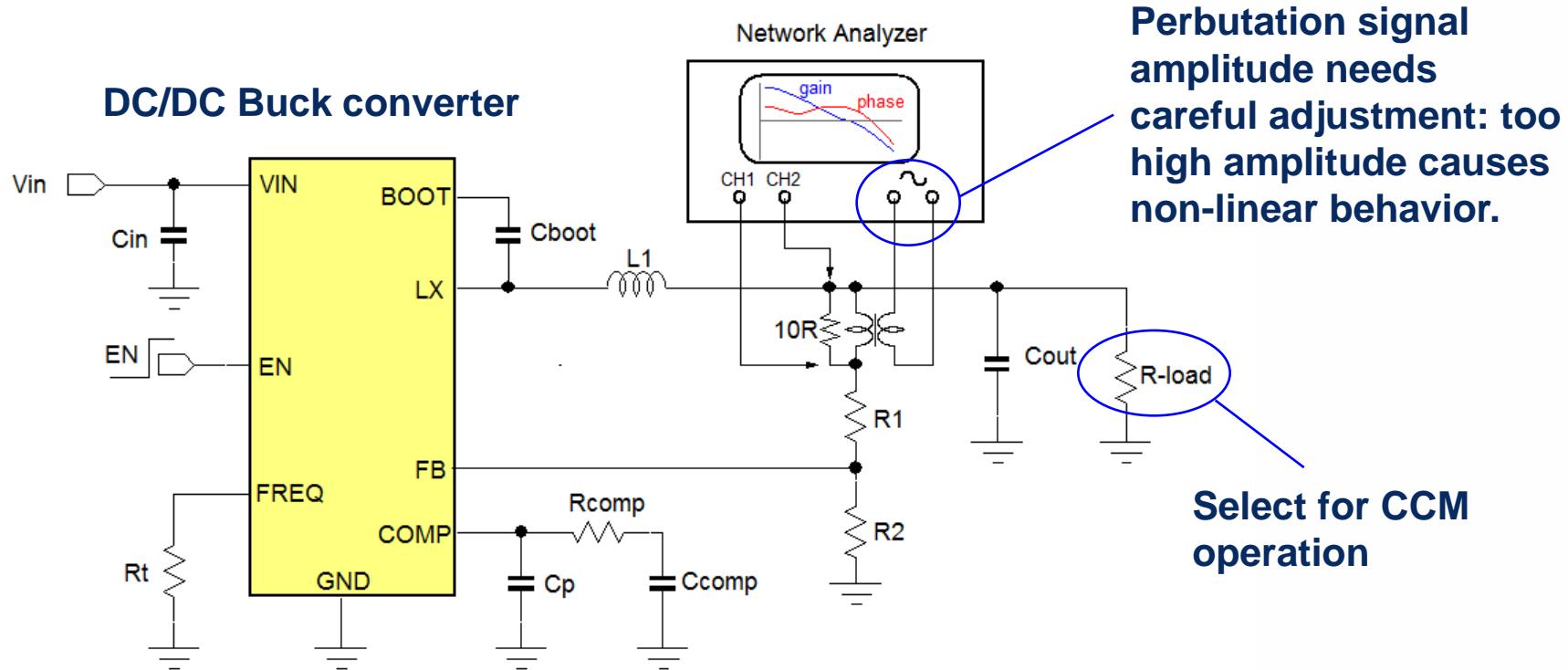
Richtek Field Application Engineering

December, 2016

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Converter stability check methods (I)

Frequency Domain Open Loop Gain-Phase Analysis

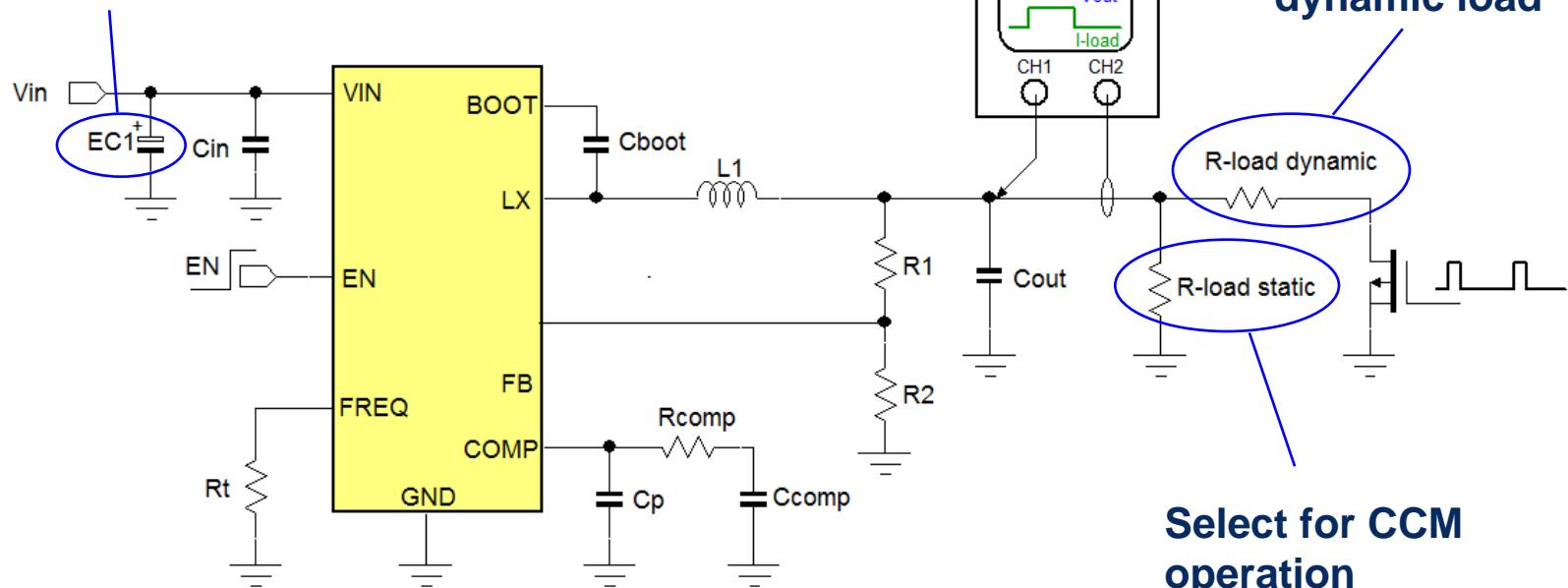


- + Good overview of critical loop parameters
- Complicated measurement
- Prone to noise pick-up and non-linear effects

Converter stability check methods (II)

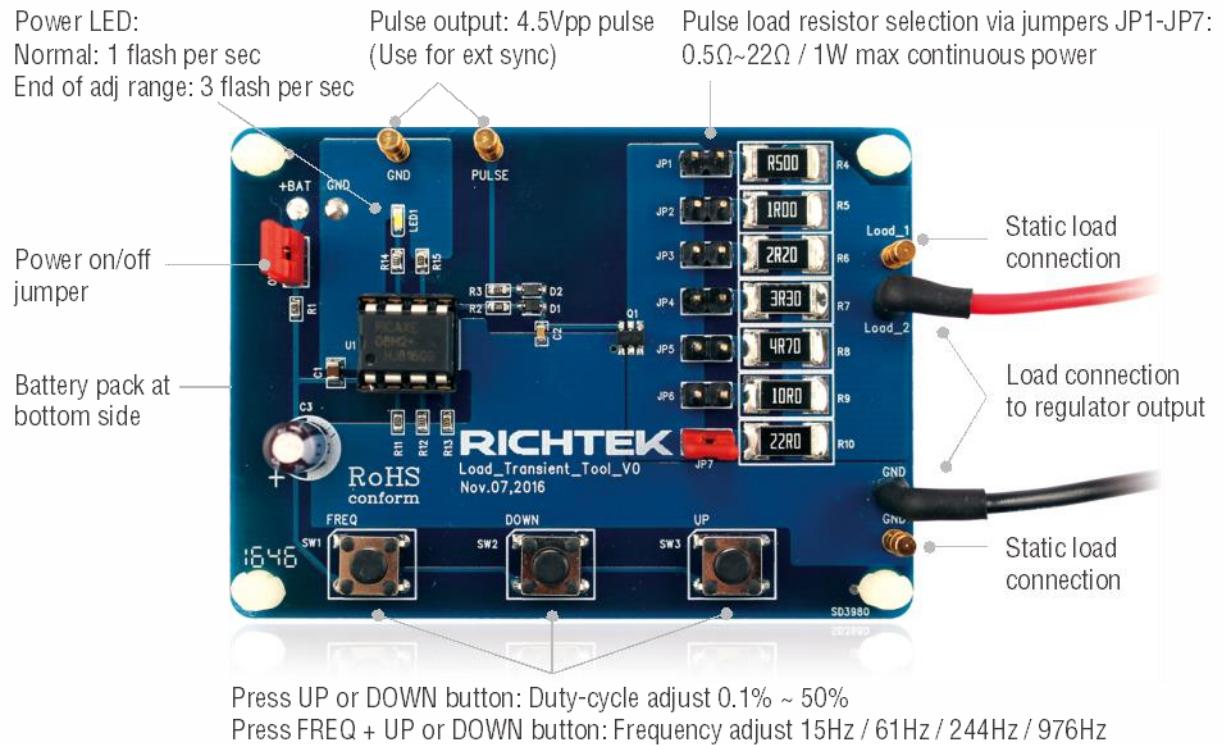
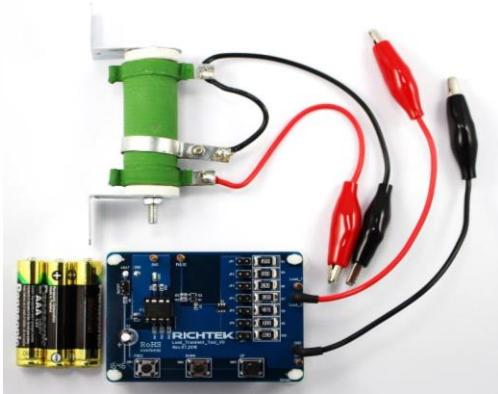
Time Domain Fast Load Transient Analysis

Add electrolytic input capacitor to avoid input ringing



- + Simple measurement
- + Can show various converter response effects
- Needs some skill to interpret the output waveform

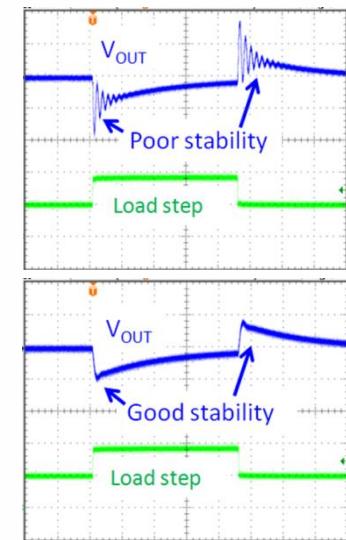
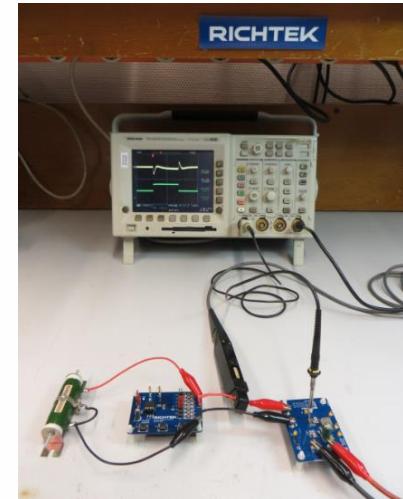
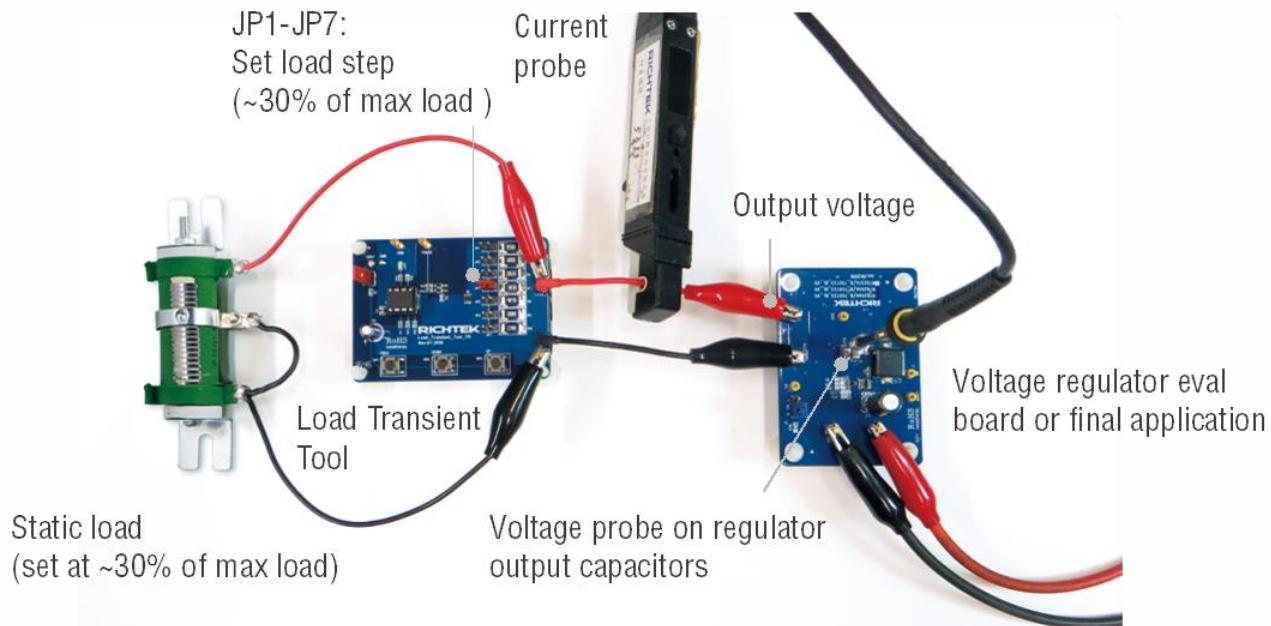
Richtek Load Transient Tool (I)



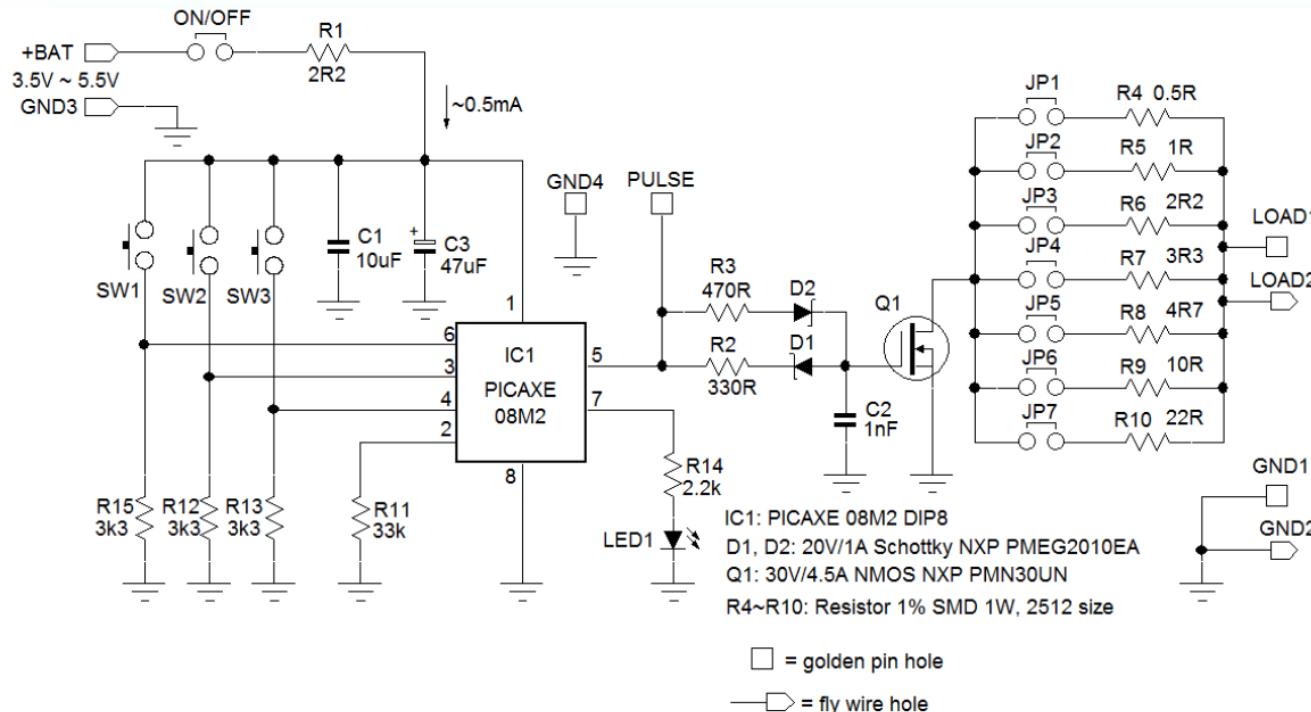
The Richtek Load Transient Tool contains a micro controller that switches a MOSFET on and off with a certain duty-cycle. By means of jumpers, 7 different pulse load resistors can be selected. The tool includes an adjustable 10Ω power resistor for setting the static load level. This tool can generate fast load steps (~500nsec rise/fall times), and the pulse load duty-cycle and frequency are adjustable by means of push buttons. The tool is battery powered, so it can easily be applied to any voltage regulator output in your system.

Richtek Load Transient Tool measurement setup

The Load transient tool is intended to be used for testing voltage regulators (buck, boost, LDO) with output voltage between 1V and 5V and maximum 5A current rating, but basically it can be used for testing any voltage regulator output. Just apply the pulse load leads to the converter output, adjust the static load resistor for CCM (continuous current mode) or ~ 30% of rated load, select the pulse load resistor for ~ 30% of rated load, measure the pulse current and the regulator output voltage across the output capacitors. Adjust the pulse load duty-cycle / frequency to see the full step load response.



Richtek Load Transient Tool schematic



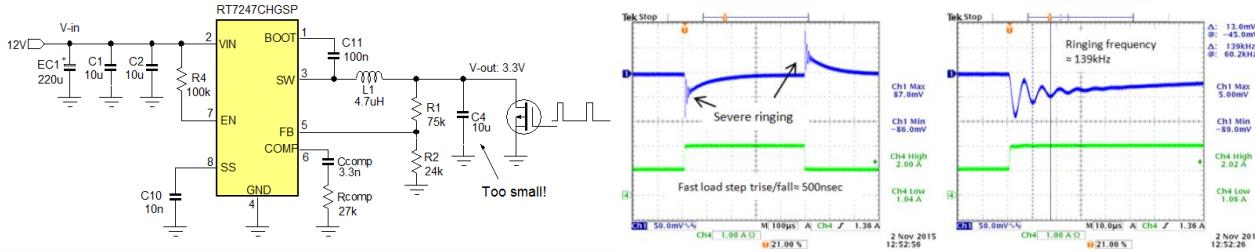
The above schematic shows the micro controller that drives the MOSFET switch. The MOSFET gate drive is designed to generate equal switching speeds with ~500nsec rise/fall times. Reducing or removing C2 can increase the switching speed, but the actual load current transient speed is mostly determined by the wiring inductance between the tool and the application. Especially when testing low voltage supplies (< 2V), it may be necessary to use short, thick wires between the tool and the application to minimize inductance.



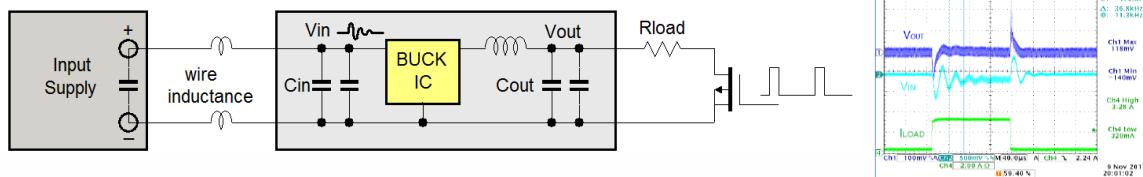
Low inductance connection

Richtek Load Transient Tool

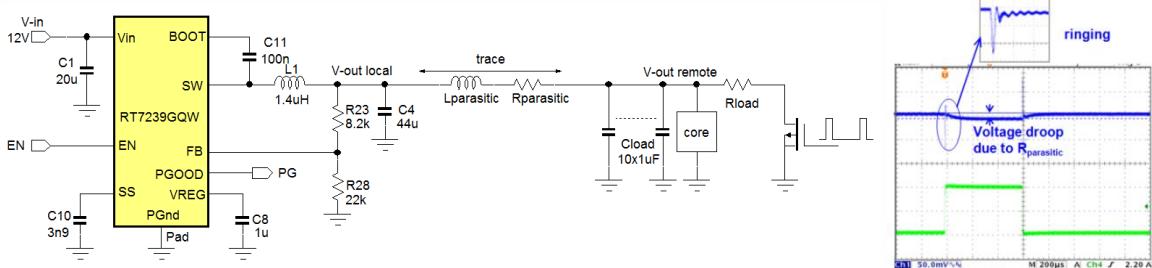
What can you do with the fast load transient tool?



Quickly check converter loop stability



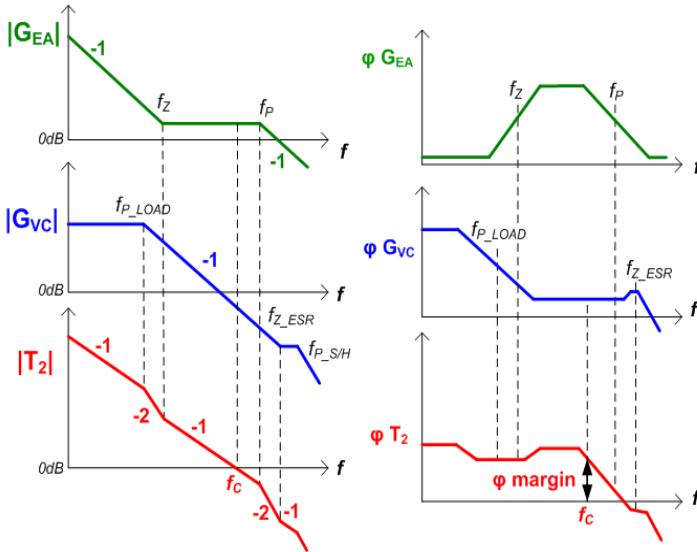
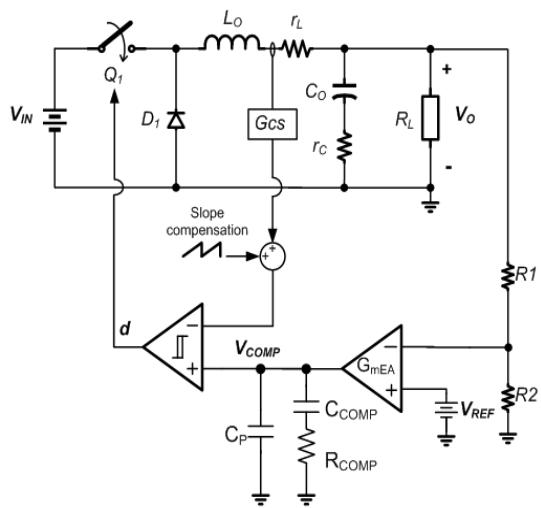
Check input supply stability



Check layout related problems

....and many more: Vout sag & soar, load regulation, slope compensation issues, estimate converter bandwidth, duty-cycle limits, check LDO, Boost, Flyback

Current Mode Buck converter control loop formula's



$$f_{P_LOAD} = \frac{1}{2\pi C_{OUT} \cdot R_{LOAD}}$$

$$f_{Z_ESR} = \frac{1}{2\pi C_{OUT} \cdot R_{ESR}}$$

$$f_Z = \frac{1}{2\pi C_{COMP} \cdot R_{COMP}}$$

$$f_P = \frac{1}{2\pi C_P \cdot R_{COMP}}$$

$$f_c = \frac{R_{COMP} \cdot G_{mEA} \cdot G_{CS}}{2\pi C_{OUT}} \cdot \frac{V_{REF}}{V_{OUT}}$$

Standard design values:

1. Set $F_{CONTROL}$ for ~ 1/10 of $F_{SWITCHING}$

$$R_{COMP} = \frac{2\pi C_{OUT} \cdot 0.1 F_{SW}}{G_{mEA} \cdot G_{CS}} \cdot \frac{V_{OUT}}{V_{REF}}$$

2. F_Z to be just below F_{P_LOAD}

$$C_{COMP} \geq \frac{C_{LOAD} \cdot R_{LOAD}}{R_{COMP}}$$

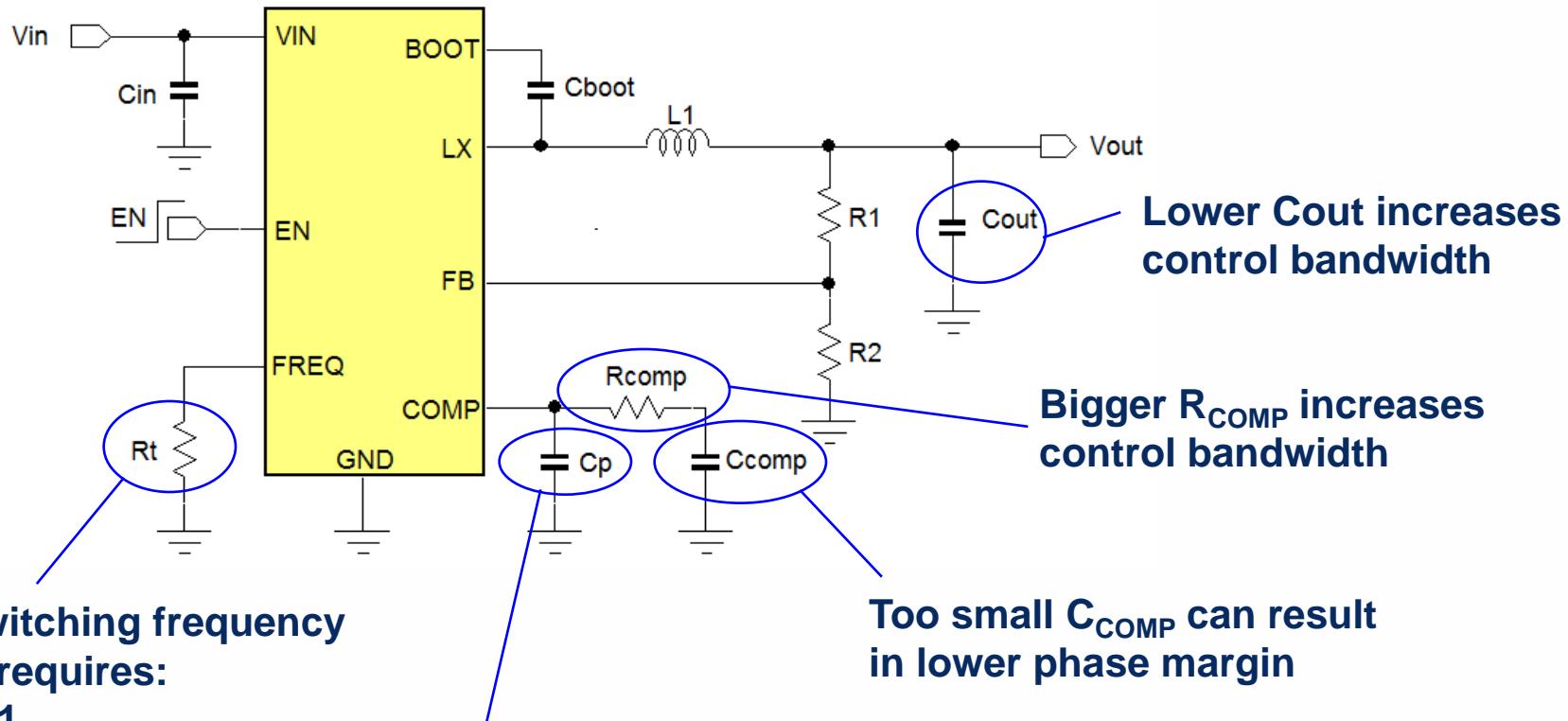
3. F_P to be close to F_{Z_ESR}

$$C_P = \frac{C_{OUT} \cdot R_{ESR}}{R_{COMP}}$$

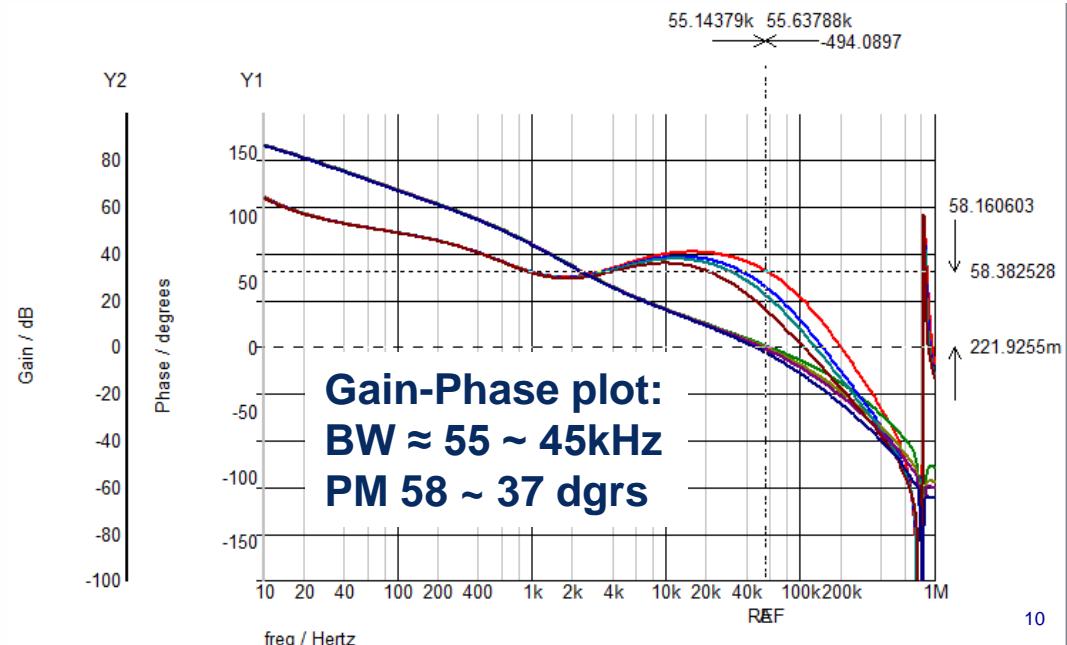
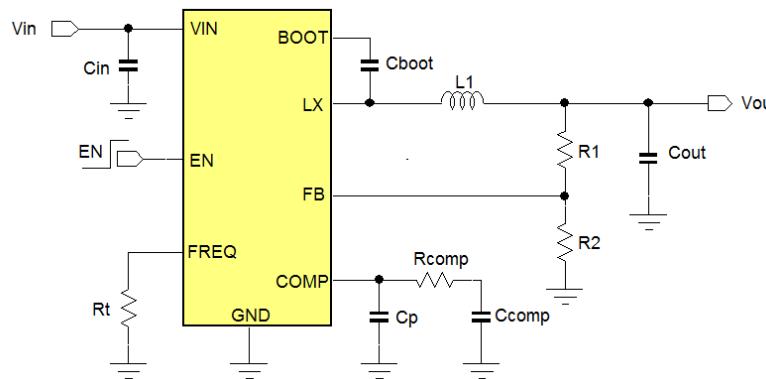
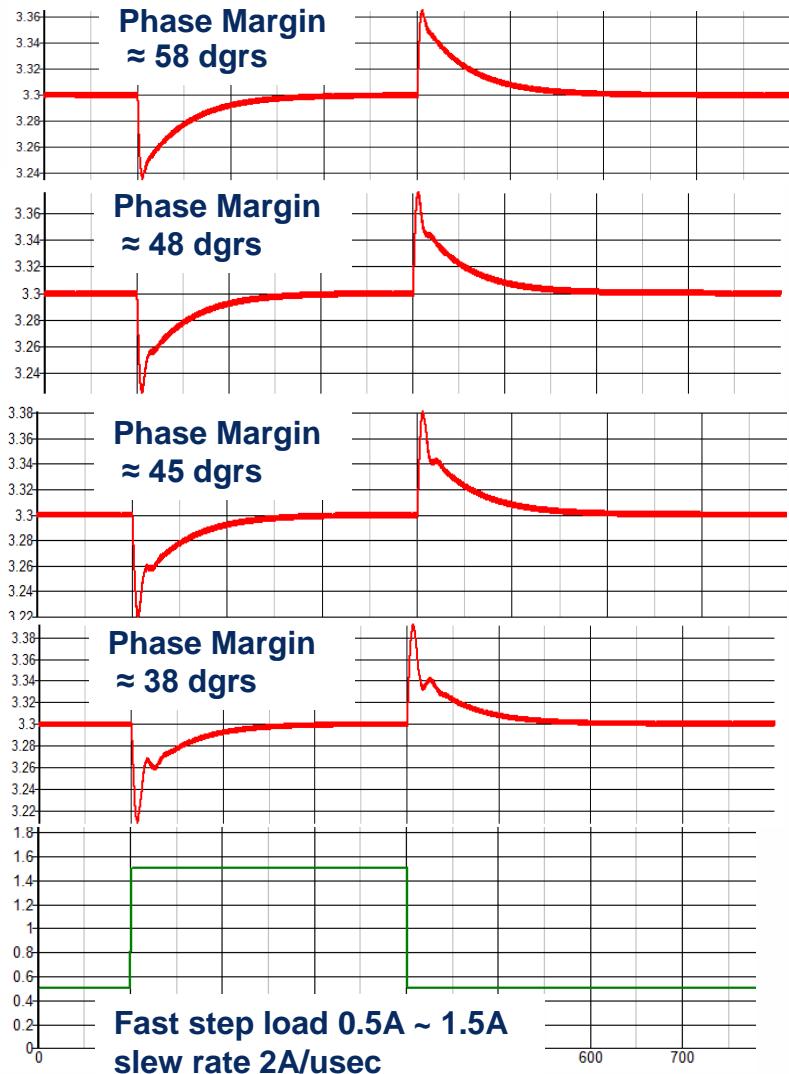
(in noisy application with MLCC Cout, F_P can be set between 0.5 ~ 1* $F_{SWITCHING}$)

Current Mode Buck converter

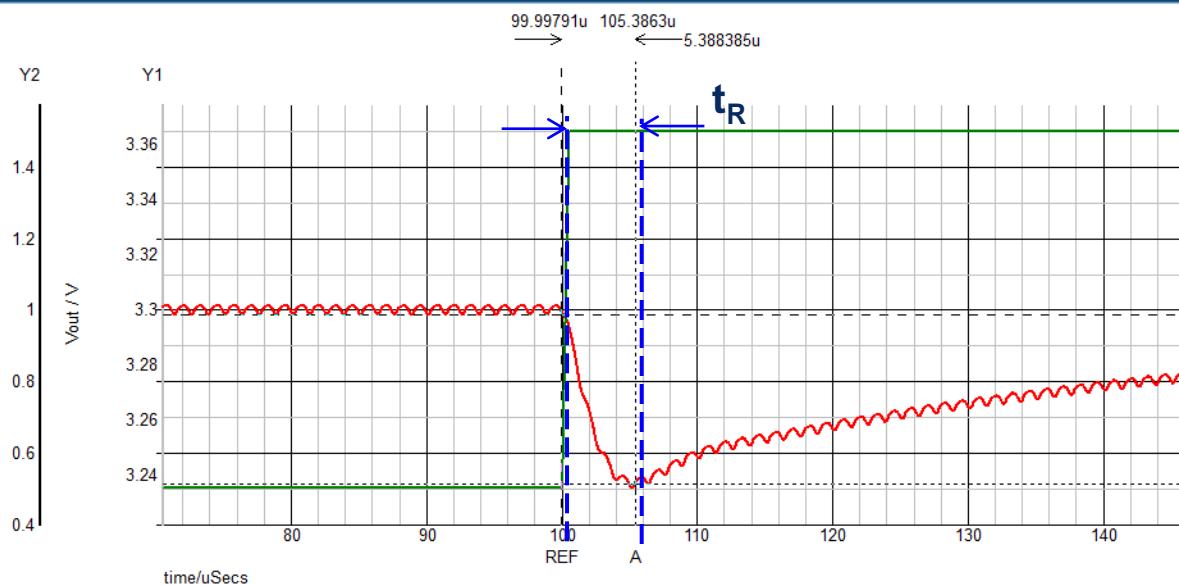
Components that influence Current Mode Buck converter loop stability



Example of Fast Transient response vs. Phase Margin



What else can you learn from Fast Transient response?



Response time t_R is a rough indication of the control bandwidth:

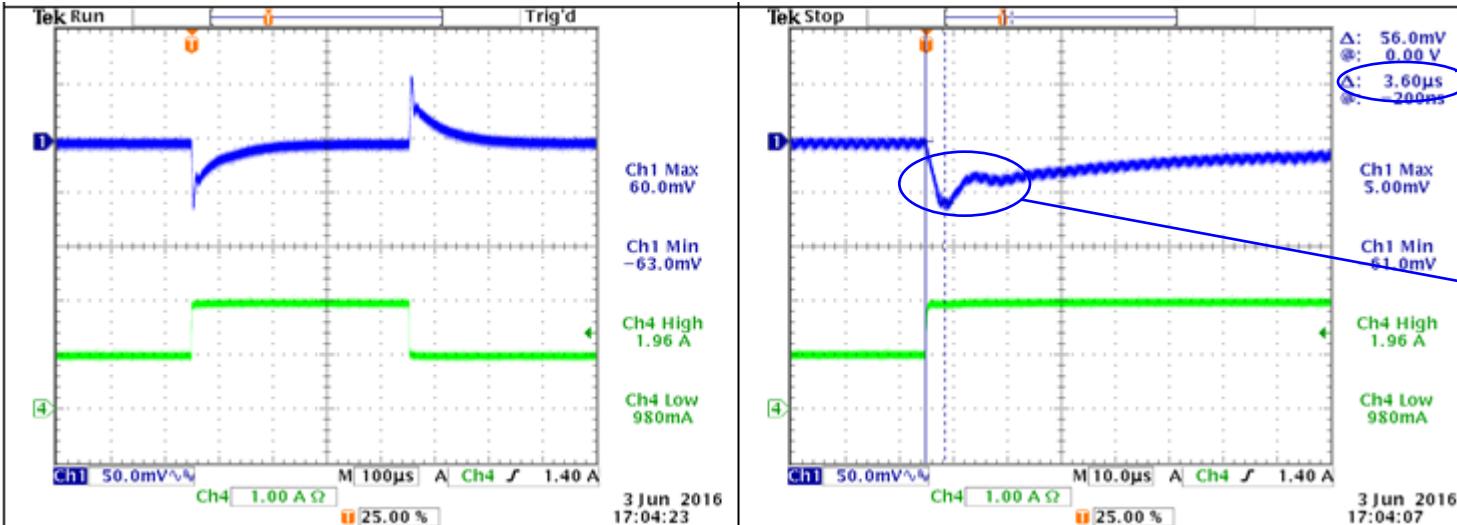
**For most current mode buck converters:
Bandwidth $BW \approx 0.3 / t_R$**

In this example:

$$t_R = 5.3\text{usec} \rightarrow BW \approx 0.3/5.3\text{usec} = 57\text{kHz}$$

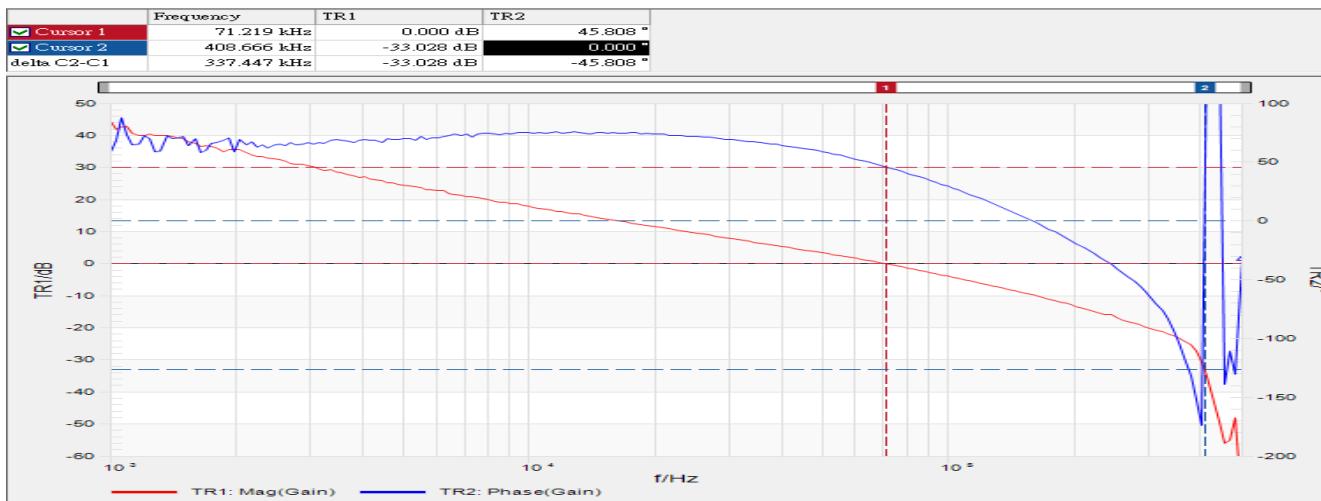
**Note: Load step rise time must be << than $1/F_C$.
→ Choose load step rise time around 500nsec**

Actual measurement example



$t_R = 3.6\text{usec} \rightarrow$
 $\text{BW} \approx 0.3/3.6\text{usec}$
 $= 83\text{kHz}$

Single bump: \rightarrow
 $\text{PM} \approx 45 \text{ dgs}$



Actual Gain-Phase measurement:

Measured BW = 72kHz
Measured PM = 45.8 dgs

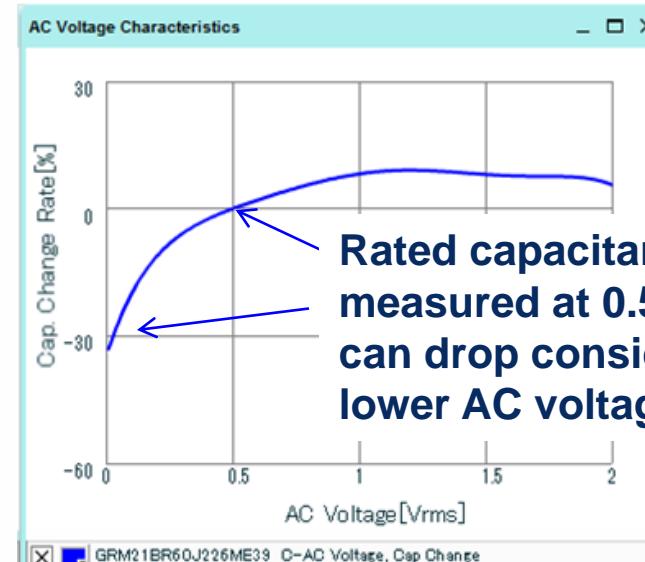
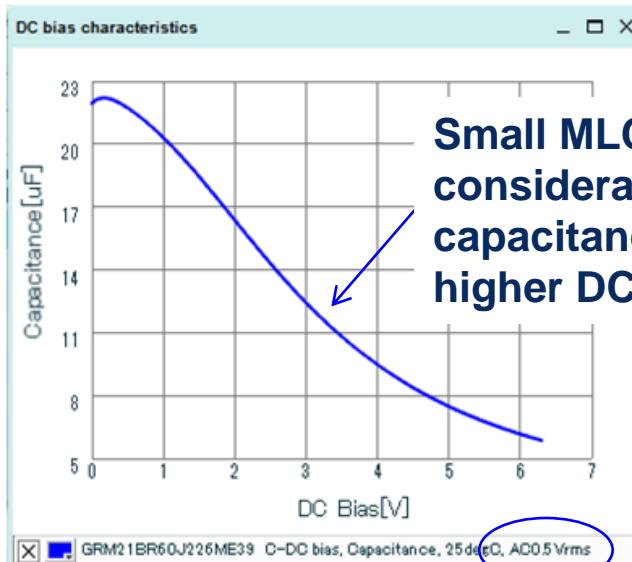
Output capacitor value is critical for loop stability!

$$f_C = \frac{R_{COMP} \cdot G_{mEA} \cdot G_{GS}}{2\pi C_{OUT}} \cdot \frac{V_{REF}}{V_{OUT}}$$

Smaller output capacitor increases BW!

Source:
[http://ds.murata.com
/software/simsurfing/en-us/](http://ds.murata.com/software/simsurfing/en-us/)

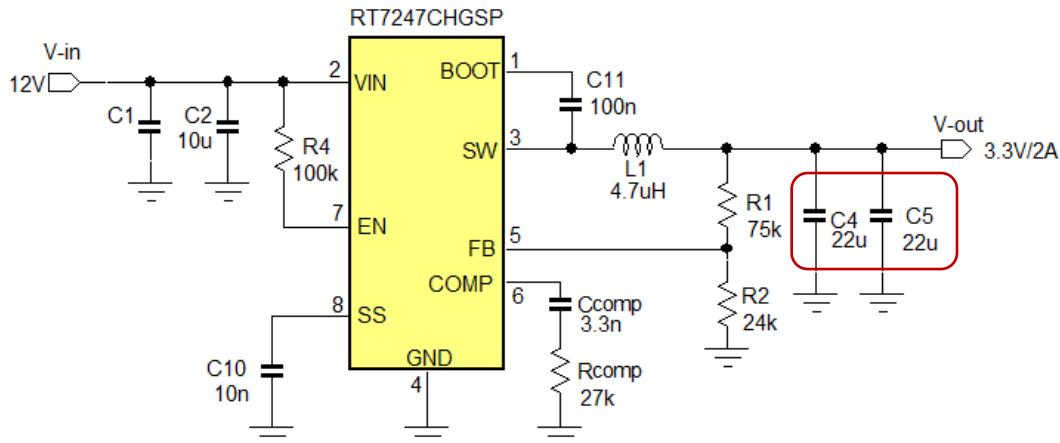
Be aware of MLCC capacitor DC bias and AC ripple characteristics:



(if DC bias or AC voltage effect is not specified for your capacitor type, ask for it)

→ Always use actual capacitance when designing the control loop!

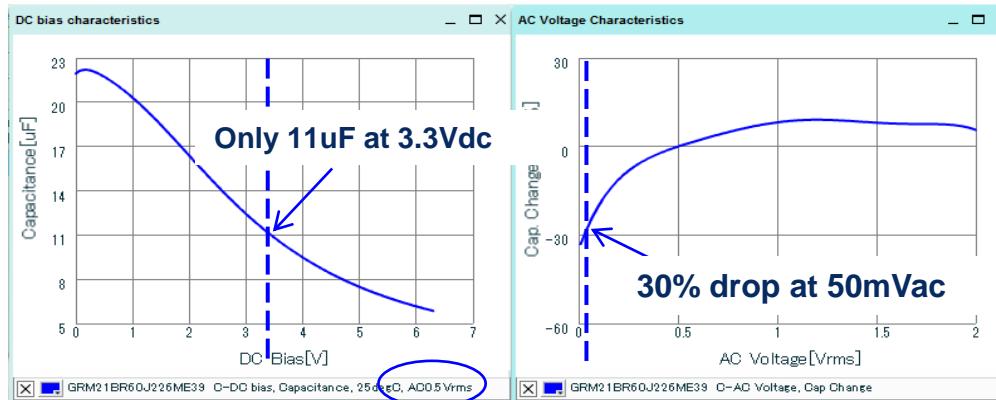
Practical example on output capacitor influence (I)



800kHz converter designed for 2x22uF output capacitance in 3.3V output application.

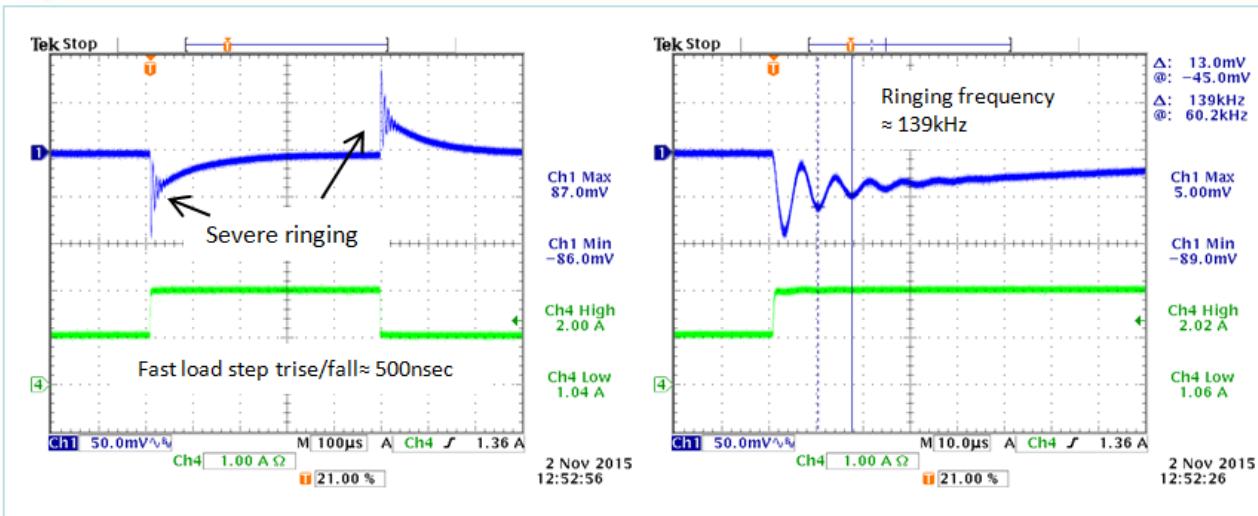
Circuit was designed for BW = 69kHz and PM = 59dgs

Designer selects 2x 22 μ F / 6.3V 0805 MLCC: GRM21BR60J226ME39L



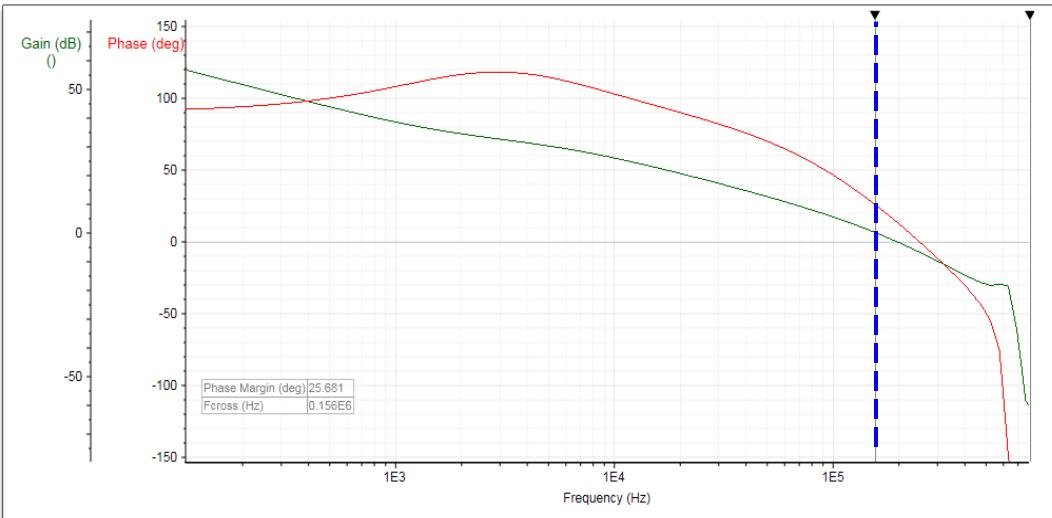
Actual capacitance is $11\mu\text{F} * 0.7 = 8\mu\text{F}$: total output capacitance **16uF instead of 44uF**
Converter Bandwidth will become $44/16 = 2.75$ times higher than design value.

Practical example on output capacitor influence (II)



Step load shows severe ringing with ringing frequency of 139kHz

(Ringing frequency indicates Fc value)



Circuit simulation using online Richtek Designer tool and using 16uF output capacitance confirms the step load result:

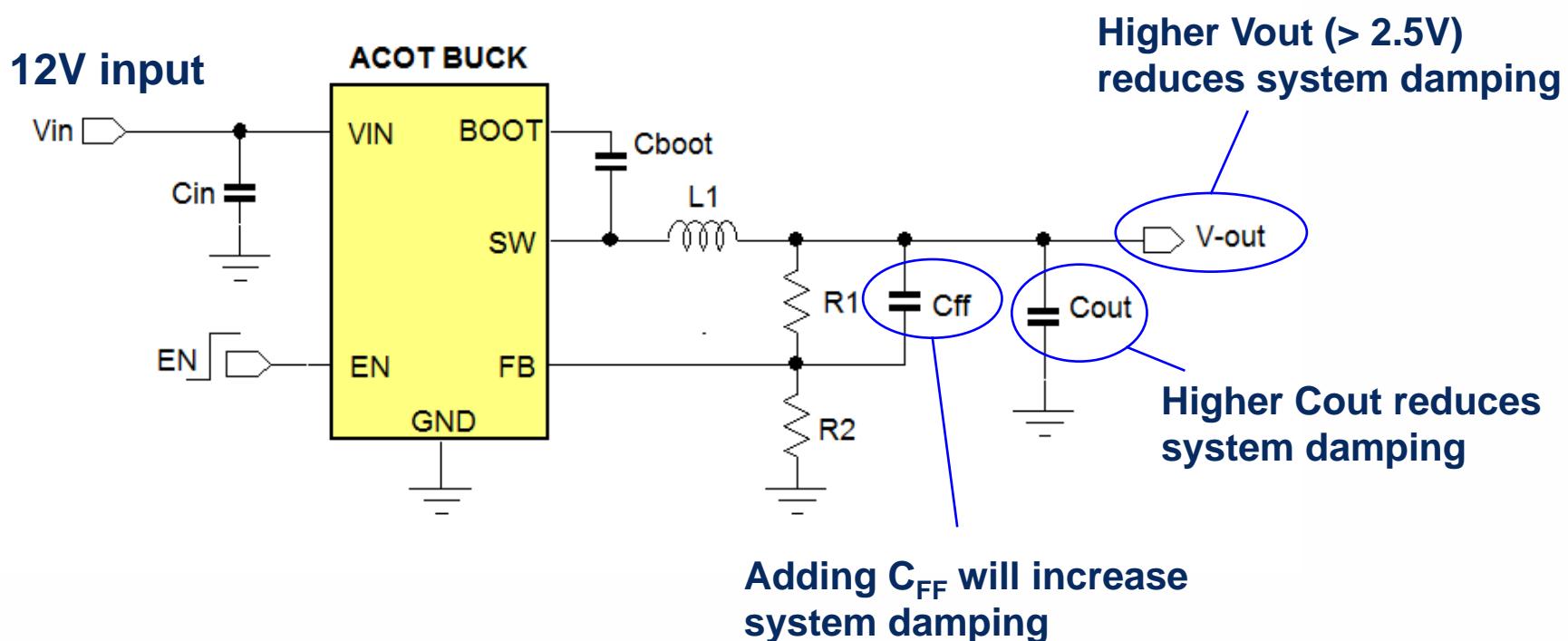
BW = 156kHz and PM = 26dgs

→ You can reduce R_{COMP} to reduce the BW to original design value for better PM.

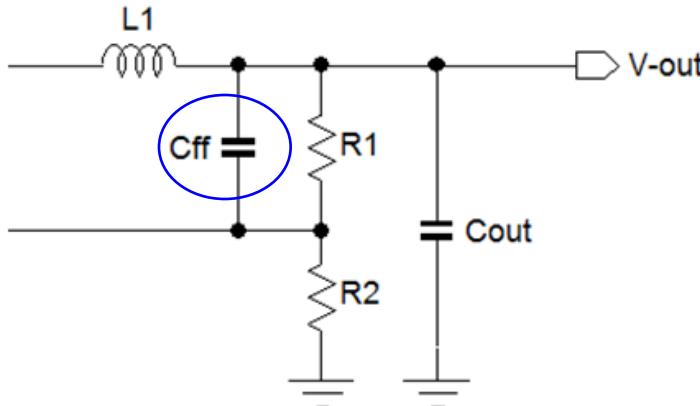
ACOT™ Buck converter stability

ACOT buck converters are much less critical in stability compared to current mode buck converters.

Normally applications with higher duty-cycle ($> 20\%$) or large value output capacitors need to add some C_{FF} to increase system damping.

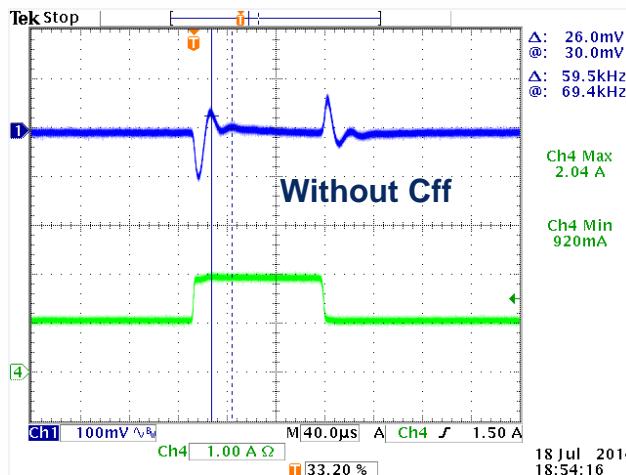


ACOT converter stability: How to tune Cff



The feed-forward capacitor plays a role in the damping of the ACOT control loop, especially at higher duty-cycle applications like $12V \rightarrow 5V$. For low duty-cycle applications like $12V \rightarrow 1V$ it is normally not needed. The value of Cff for a specific ACOT converter depends on duty-cycle, C_{OUT} value, inductor value and R1 value.

Practical method to find Cff value:



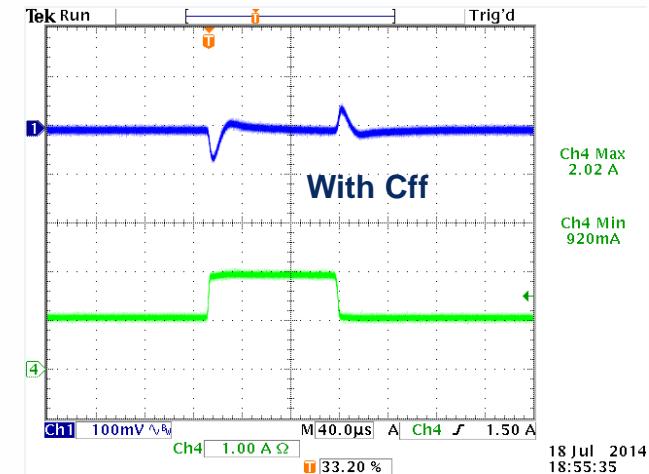
2. Calculate Cff by the formula:

$$C_{FF} = \frac{1}{2\pi \cdot R_1 \cdot f_{RING} \cdot 0.8}$$

In this example: ($R_1 = 120k$)

$$\frac{1}{2\pi \cdot 120k \cdot 59.5k \cdot 0.8} = 27.9\text{pF}$$

1. Apply a fast step load and if it shows ringing, measure the ringing frequency
In this $12V \rightarrow 5V$ example: $f_{RING}=59.5\text{kHz}$



After adding $Cff = 27\text{pF}$: well-damped step response

Relevant Richtek application note

AN038: Fast Load Transient Testing

Richtek Application AN038

Practical hints and tips on converter stability testing using fast load transients

Let's show this with the below example where a RT7294CGJ6F, a low cost 18V/2.5A ACOT buck IC in SOT-23-6 is used to make a 1V core supply rail:

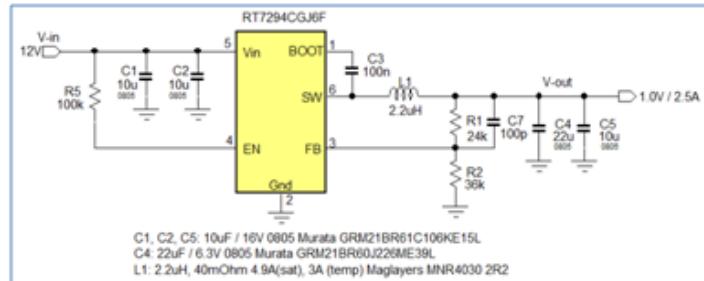


FIGURE 41

ACOT converters have a fixed ON time and a variable OFF time and can react very quickly to load changes. The converter maximum duty-cycle is limited by the CM voltage. When the load step occurs, the ACOT converter can achieve a low load step response. At the start of the low load step occurs, the ACOT converter reduces current down as fast as possible, temporarily

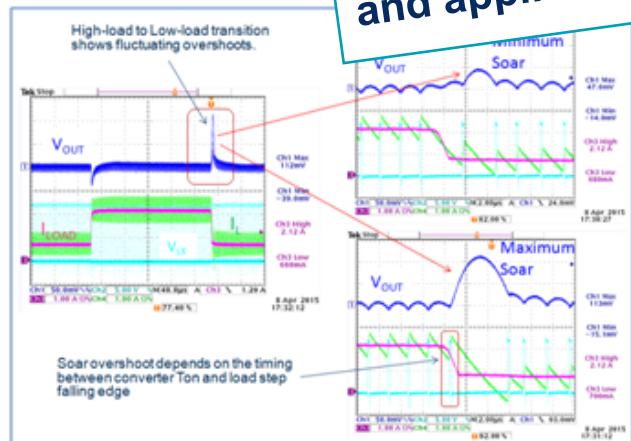
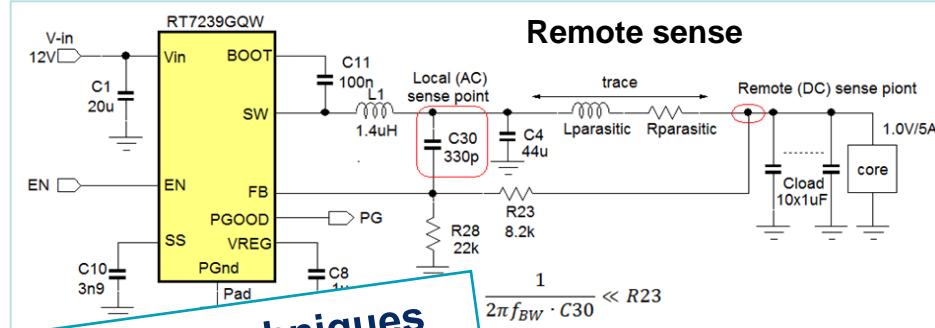


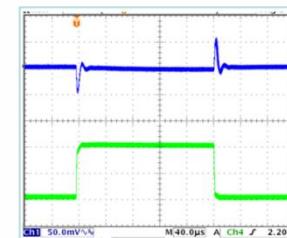
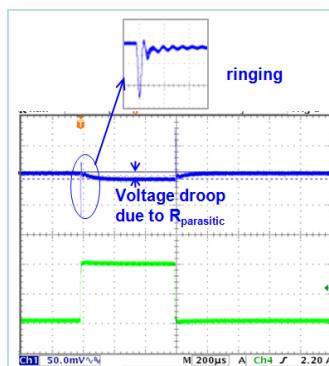
FIGURE 42

Technical explanation, measurement techniques and application examples



$$R_{SNUBBER} = \sqrt{\frac{L_{PARASITIC}}{C_{LOAD}}} \approx \sqrt{\frac{30\mu H}{10\mu F}} = 55m\Omega$$

$$C_{SNUBBER} = \frac{2\pi\sqrt{L_{PARASITIC} \cdot C_{LOAD}}}{R_{SNUBBER}} \approx \frac{2\pi\sqrt{30\mu H \cdot 10\mu F}}{55m\Omega} = 62\mu F$$



Richtek Designer online tool

Full simulation of application circuit

1 Part Selection 2 Design Requirements 3 Analyze 4 Efficiency 5 BOM 6 Summary Quick Start Guide Online Technical Help

RT2875BQGCP 3A, 36V, Current Mode Synchronous Step-Down Converter, with Resistor-Adjustable Frequency and Current Limit, UVP Hiccup

Steady-State Analysis Transient Analysis Startup Analysis AC Analysis

Fully Configurable Schematic

Load Transient

Current Limit effects

Gain-Phase tolerance analysis

Efficiency & IC power loss

Recommended Component BOM

Register today!

The screenshot displays the '3 Analyze' tab of the Richtek Designer tool. At the top, tabs for 'Steady-State Analysis', 'Transient Analysis', 'Startup Analysis', and 'AC Analysis' are shown, with 'Transient Analysis' being the active tab. Below these tabs is a 'Fully Configurable Schematic' of a RT2875BQGCP circuit. Surrounding the schematic are five boxes containing analysis results: 'Load Transient' (a graph of current vs. time), 'Current Limit effects' (a graph of current vs. time showing a limit being reached), 'Gain-Phase tolerance analysis' (a graph of phase margin vs. frequency with annotations for crossover frequency and phase margin), 'Efficiency & IC power loss' (two graphs showing efficiency and power loss vs. frequency), and 'Recommended Component BOM' (a table of component details). A 'Register today!' button is located at the bottom left.

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thank you.