

## Dual High Efficiency PWM Step-Down DC/DC Converter

### General Description

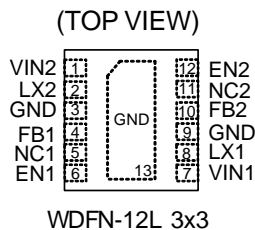
The RT8020H is a dual high efficiency Pulse-Width-Modulated (PWM) step-down DC/DC converter. It is capable of delivering 1A output current over a wide input voltage range from 2.5V to 5.5V. The RT8020H is ideally suited for portable electronic devices that are powered by 1-cell Li-ion battery or other power sources within the range such as cellular phones, PDAs and other hand-held devices.

Two operational modes are available : PWM/Low-Dropout auto-switch mode and shutdown mode. Internal synchronous rectifier with low  $R_{DS(ON)}$  dramatically reduces conduction loss at PWM mode. No external Schottky diode is required in practical application.

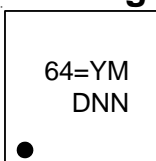
The RT8020H enters Low-Dropout mode when normal PWM cannot provide regulated output voltage by continuously turning on the upper PMOS. The RT8020H enters shutdown mode and consumes less than 0.1 $\mu$ A when the EN pin is pulled low.

The switching ripple is easily smoothed-out by small package filtering elements due to a fixed operation frequency of 1.5MHz. This, along with a small WDFN-12L 3x3 package, provides an ideal solution for small PCB area application. Other features include soft start, lower internal reference voltage with 2% accuracy, over temperature protection, and over current protection.

### Pin Configurations



### Marking Information



64= : Product Code  
YMDNN : Date code

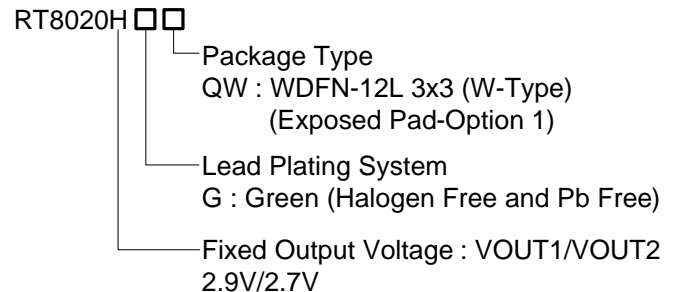
### Features

- 2.5V to 5.5V Input Range
- 2.9V and 2.7V Fixed Output Voltage
- 1A Output Current
- 95% Efficiency
- No Schottky Diode Required
- 50 $\mu$ A Quiescent Current per Channel
- 1.5MHz Fixed Frequency PWM Operation
- Small 12-Lead WDFN Package
- RoHS Compliant and Halogen Free

### Applications

- Digital Still Cameras
- Mobile Phones
- Personal Information Appliances
- Wireless and DSL Modems
- MP3 Players
- Portable Instruments

### Ordering Information

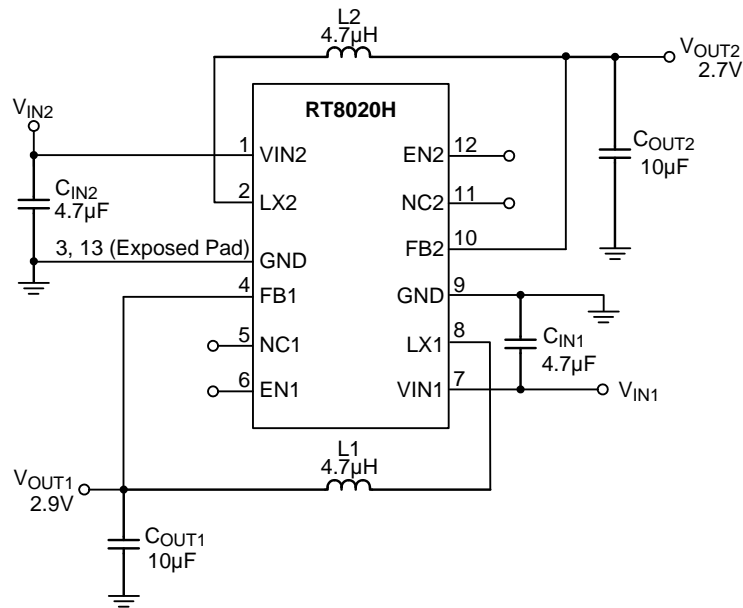


Note :

Richtek products are :

- ▶ RoHS compliant and compatible with the current requirements of IPC/JEDEC J-STD-020.
- ▶ Suitable for use in SnPb or Pb-free soldering processes.

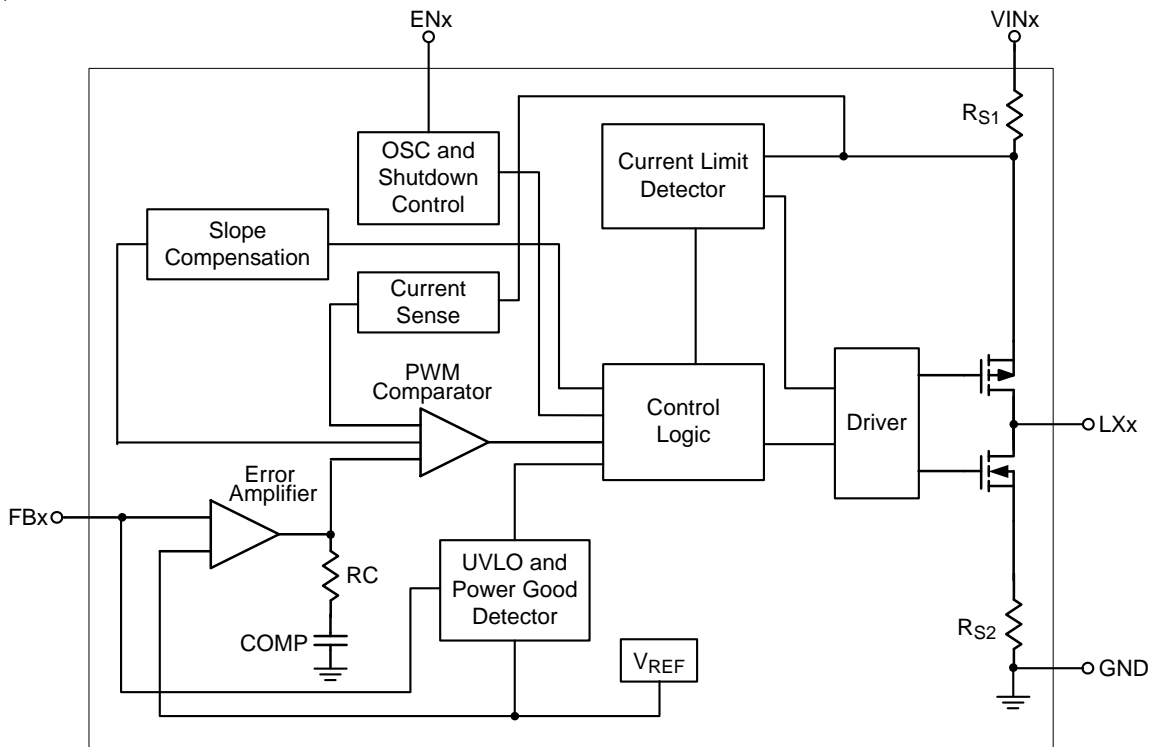
## Typical Application Circuit



## Functional Pin Description

Pin No.	Pin Name	Pin Function
1	VIN2	Power Input of Channel 2.
2	LX2	Pin for Switching of Channel 2.
3, 9, 13 (Exposed Pad)	GND	Ground. The exposed pad must be soldered to a large PCB and connected to GND for maximum power dissipation.
4	FB1	Feedback of Channel 1.
5, 11	NC1, NC2	No Connection or Connect to $V_{IN}$ .
6	EN1	Chip Enable of Channel 1 (Active High). $V_{EN1} \leq V_{IN1}$ .
7	VIN1	Power Input of Channel 1.
8	LX1	Pin for Switching of Channel 1.
10	FB2	Feedback of Channel 2.
12	EN2	Chip Enable of Channel 2 (Active High). $V_{EN2} \leq V_{IN2}$ .

**Function Block Diagram**



## Absolute Maximum Ratings (Note 1)

- Supply Input Voltage,  $V_{IN1}$ ,  $V_{IN2}$  ----- -0.3V to 6.5V
- EN1, FB1, LX1, EN2, FB2 and LX2 Pin Voltage ----- -0.3V to ( $V_{IN} + 0.3V$ )
- LX1 to GND, LX2 to GND (<200ns) ----- -1.5V to 7.5V
- Power Dissipation,  $P_D$  @  $T_A = 25^\circ C$ 
  - WDFN-12L 3x3 ----- 1.667W
- Package Thermal Resistance (Note 2)
  - WDFN-12L 3x3,  $\theta_{JA}$  -----  $60^\circ C/W$
  - WDFN-12L 3x3,  $\theta_{JC}$  -----  $8.2^\circ C/W$
- Lead Temperature (Soldering, 10 sec.) -----  $260^\circ C$
- Junction Temperature -----  $150^\circ C$
- Storage Temperature Range -----  $-65^\circ C$  to  $150^\circ C$
- ESD Susceptibility (Note 3)
  - HBM (Human Body Mode) ----- 2kV
  - MM (Machine Mode) ----- 200V

## Recommended Operating Conditions (Note 4)

- Supply Input Voltage,  $V_{IN1}$ ,  $V_{IN2}$  ----- 2.5V to 5.5V
- Junction Temperature Range -----  $-40^\circ C$  to  $125^\circ C$
- Ambient Temperature Range -----  $-40^\circ C$  to  $85^\circ C$

## Electrical Characteristics

( $V_{IN} = 3.6V$ ,  $L = 4.7\mu H$ ,  $C_{IN} = 4.7\mu F$ ,  $C_{OUT} = 10\mu F$ ,  $I_{MAX} = 1A$ ,  $T_A = 25^\circ C$ , unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit	
<b>Channel 1 and Channel 2</b>							
Under Voltage Lockout Threshold	$V_{UVLO}$		--	1.8	--	V	
Under Voltage Lockout Hysteresis			--	0.1	--	V	
Quiescent Current	$I_Q$	$I_{OUT} = 0mA$ , $V_{FB} = V_{REF} + 5\%$	--	50	70	$\mu A$	
Shutdown Current	$I_{SHDN}$	EN = GND	--	0.1	1	$\mu A$	
Output Voltage Accuracy	$\Delta V_{OUT1}$	$V_{IN} = V_{OUT} + \Delta V$ to 5.5 (Note5), $V_{OUT1} = 2.9V$ , $0A < I_{OUT1} < 1A$	-3	--	3	%	
	$\Delta V_{OUT2}$	$V_{IN} = V_{OUT} + \Delta V$ to 5.5 (Note5), $V_{OUT2} = 2.7V$ , $0A < I_{OUT2} < 1A$	-3	--	3	%	
FB Input Current	$I_{FB}$	$V_{FB} = V_{IN}$	-50	--	50	nA	
$R_{DS(ON)}$ of P-MOSFET	$R_{DS(ON)_P}$	$I_{OUT} = 200mA$	$V_{IN} = 2.5V$	--	0.38	--	$\Omega$
			$V_{IN} = 3.6V$	--	0.28	--	
$R_{DS(ON)}$ of N-MOSFET	$R_{DS(ON)_N}$	$I_{OUT} = 200mA$	$V_{IN} = 2.5V$	--	0.35	--	$\Omega$
			$V_{IN} = 3.6V$	--	0.25	--	
P-Channel Current Limit	$I_{LIM\_P}$		1.4	1.5	--	A	
EN Input Threshold Voltage	Logic-High	$V_{IH}$	$V_{IN} = 2.5V$ to $5.5V$	1.5	--	$V_{IN}$	V
	Logic-Low	$V_{IL}$	$V_{IN} = 2.5V$ to $5.5V$	--	--	0.4	

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Oscillator Frequency	f <sub>OSC</sub>	V <sub>IN</sub> = 3.6V, I <sub>OUT</sub> = 100mA	1.2	1.5	1.8	MHz
Thermal Shutdown Temperature	T <sub>SD</sub>		--	160	--	°C
Maximum Duty Cycle	D <sub>MAX</sub>		100	--	--	%
LX Leakage Current	I <sub>LX</sub>	V <sub>IN</sub> = 3.6V, V <sub>LX</sub> = 0V or V <sub>LX</sub> = 3.6V	-1	--	1	μA

**Note 1.** Stresses listed as the above “Absolute Maximum Ratings” may cause permanent damage to the device. These are for stress ratings. Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may remain possibility to affect device reliability.

**Note 2.** θ<sub>JA</sub> is measured in natural convection at T<sub>A</sub> = 25°C on a high effective thermal conductivity four-layer test board of JEDEC 51-7 thermal measurement standard. The measurement case position of θ<sub>JC</sub> is on the exposed pad of the package.

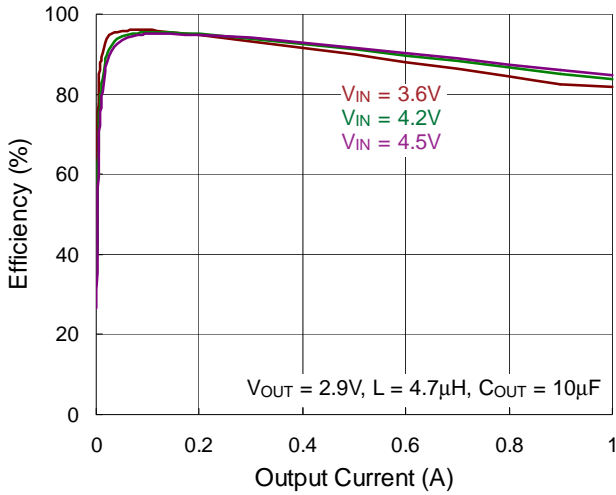
**Note 3.** Devices are ESD sensitive. Handling precaution recommended.

**Note 4.** The device is not guaranteed to function outside its operating conditions.

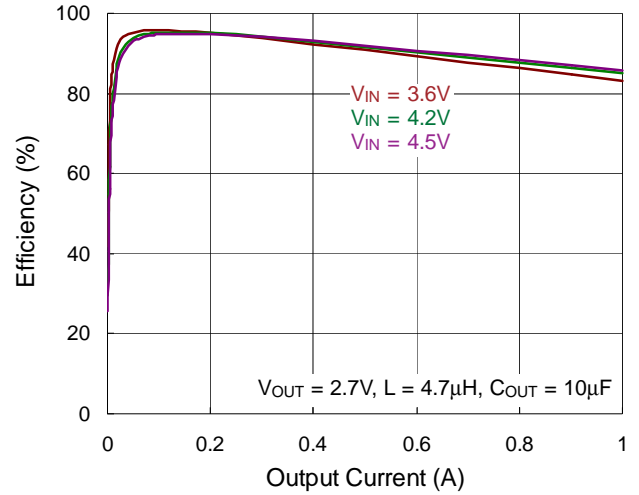
**Note 5.** ΔV = I<sub>OUT</sub> × R<sub>DS(ON)\_P</sub>

## Typical Operating Characteristics

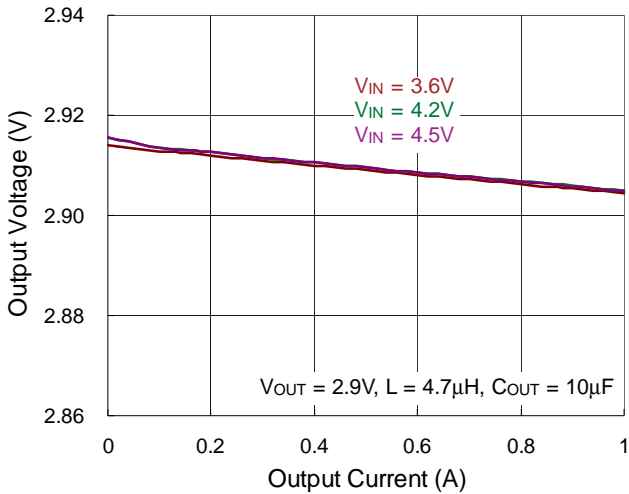
### CH1 Efficiency vs. Output Current



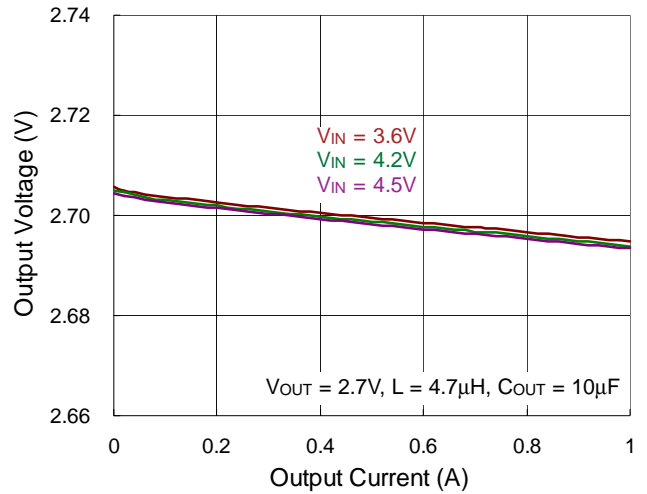
### CH2 Efficiency vs. Output Current



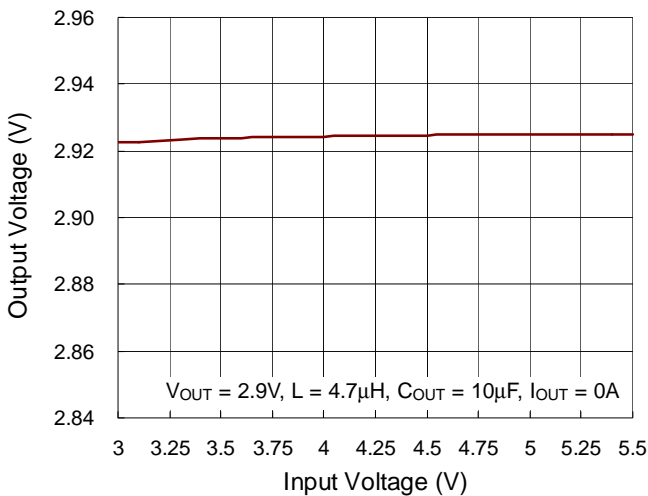
### CH1 Output Voltage vs. Output Current



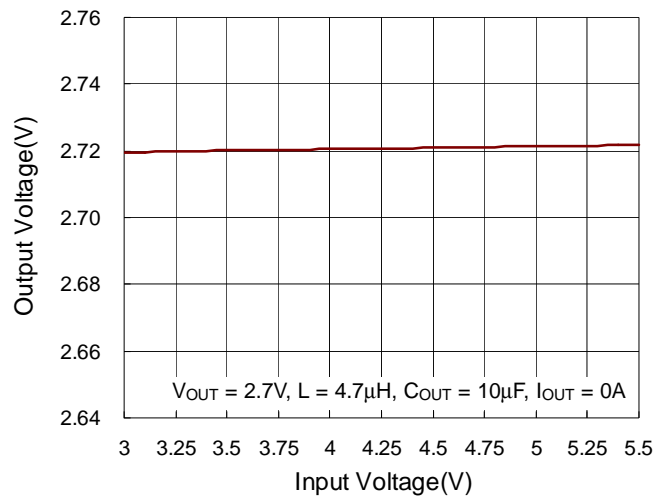
### CH2 Output Voltage vs. Output Current



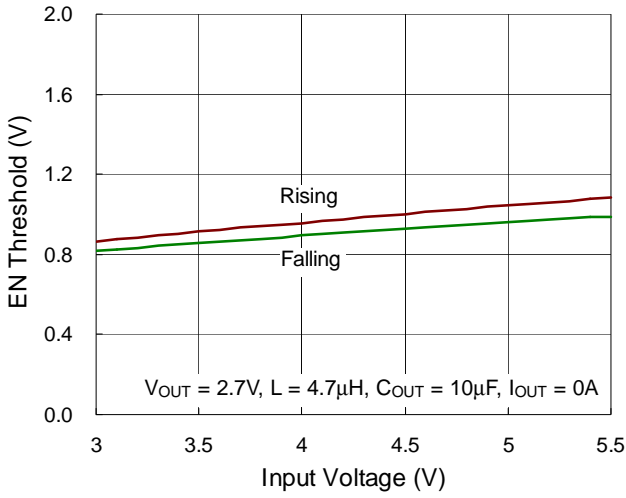
### CH1 Output Voltage vs. Input Voltage



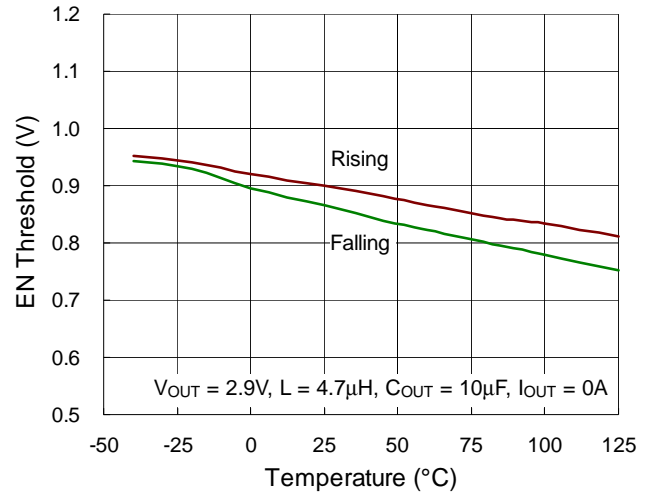
### CH2 Output Voltage vs. Input Voltage



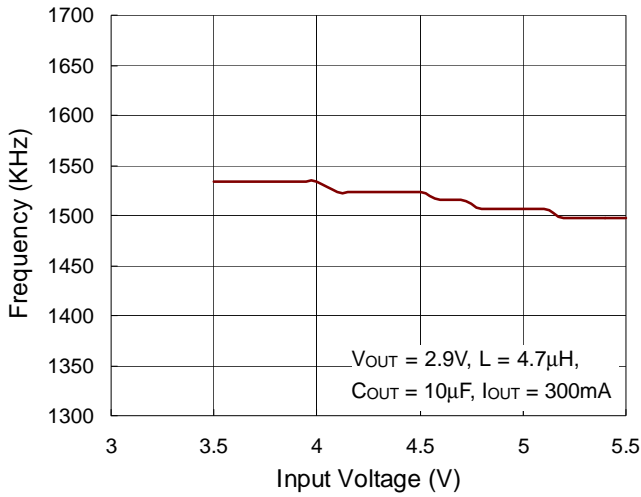
**EN Threshold vs. Input Voltage**



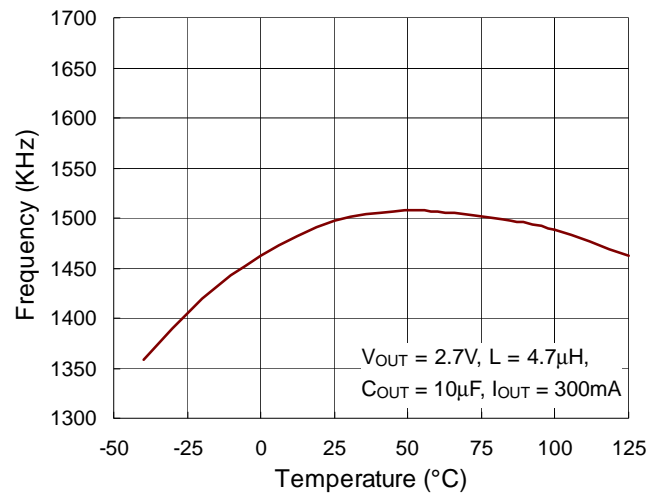
**EN Threshold vs. Temperature**



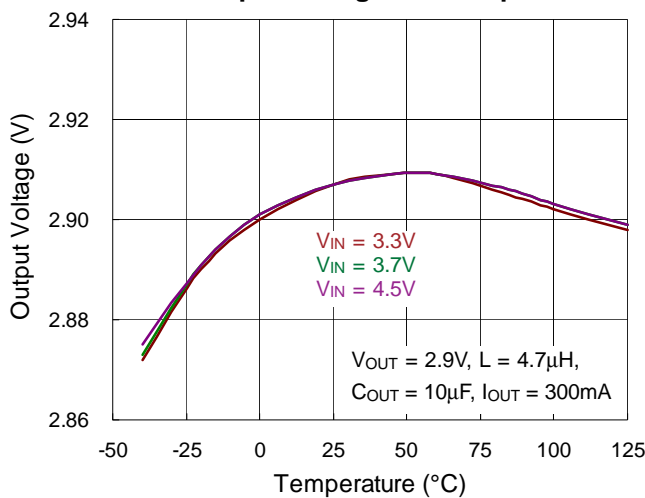
**Frequency vs. Input Voltage**



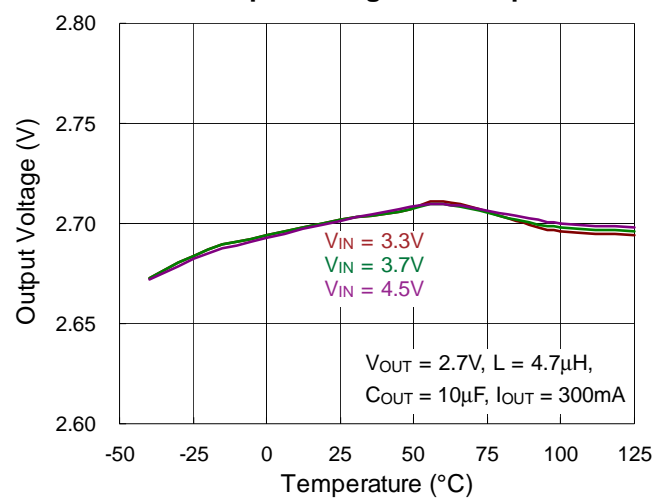
**Switching Frequency vs. Temperature**



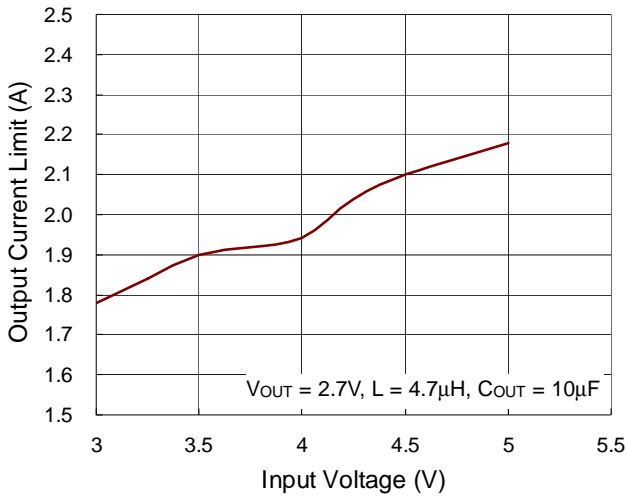
**CH1 Output Voltage vs. Temperature**



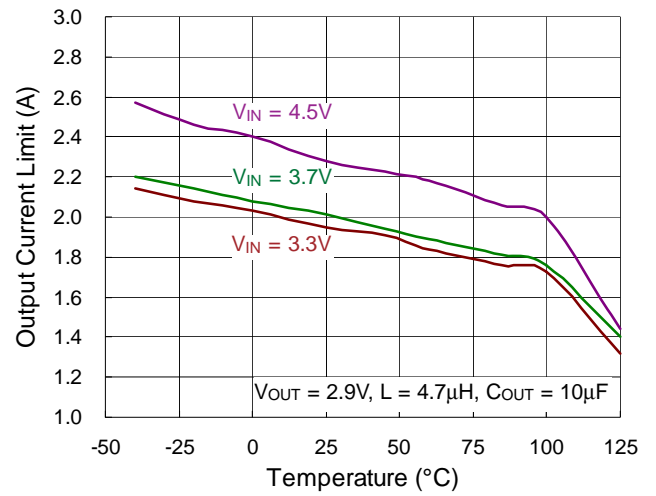
**CH2 Output Voltage vs. Temperature**



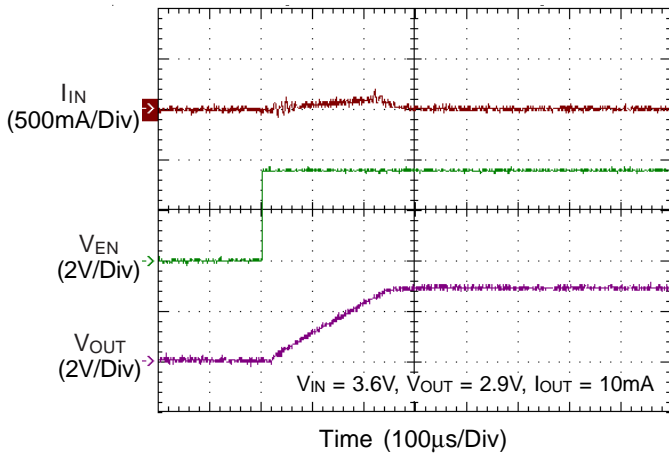
### Output Current Limit vs. Input Voltage



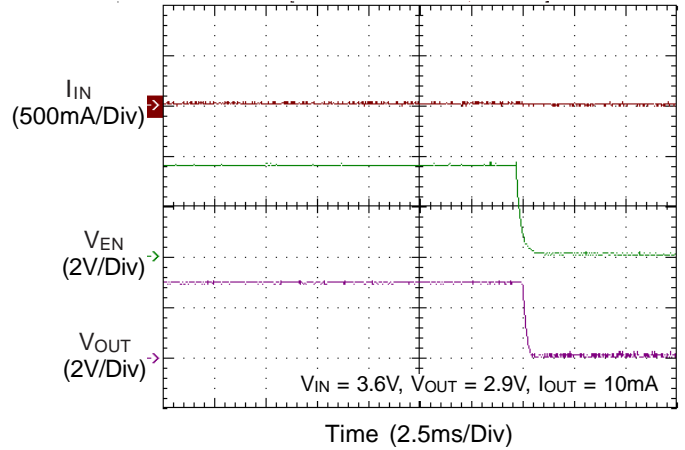
### Output Current Limit vs. Temperature



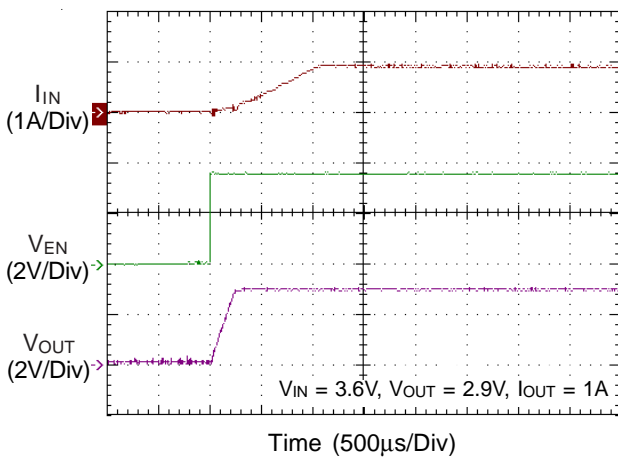
### CH1 Power On from EN



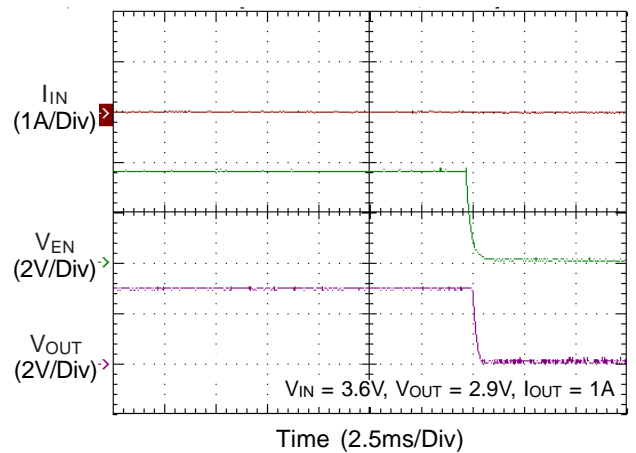
### CH1 Power Off from EN



### CH1 Power On from EN

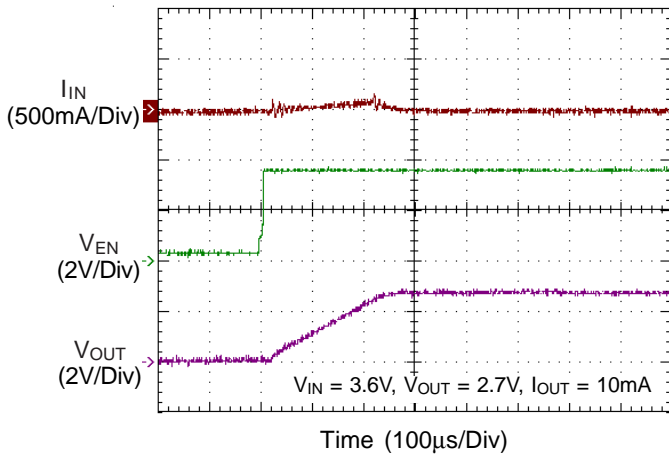


### CH1 Power Off from EN

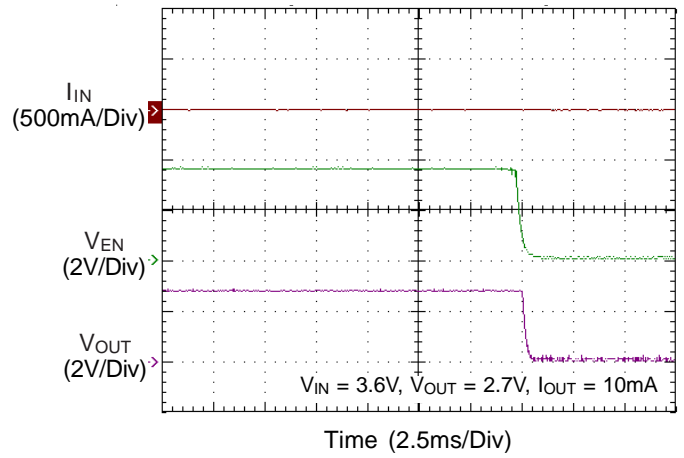




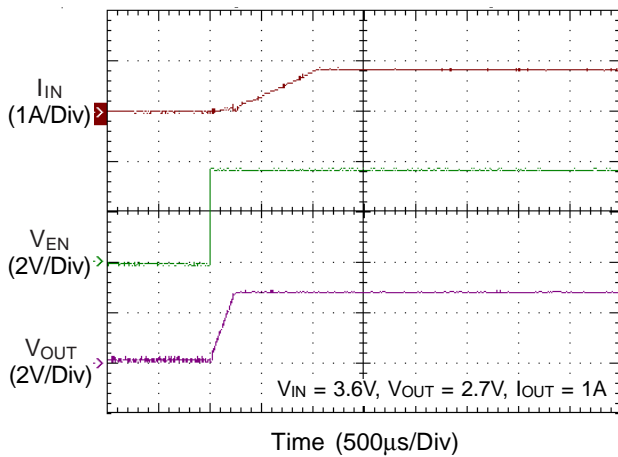
**CH2 Power On from EN**



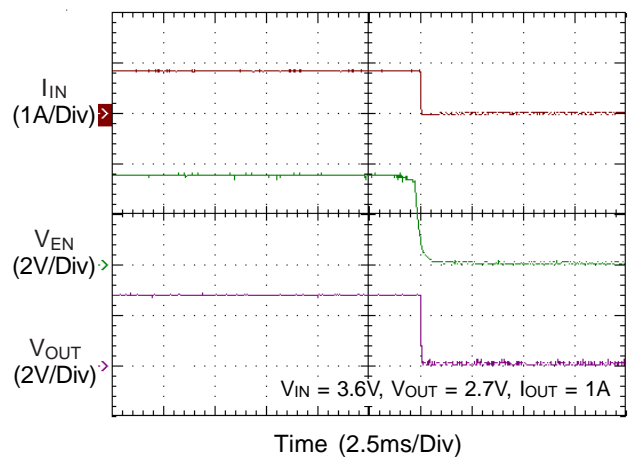
**CH2 Power Off from EN**



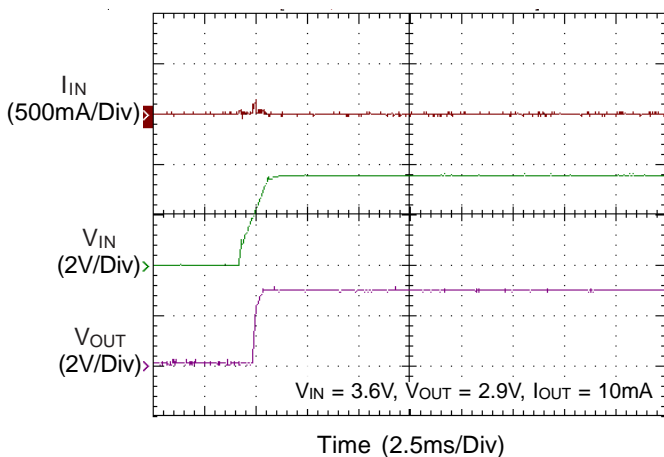
**CH2 Power On from EN**



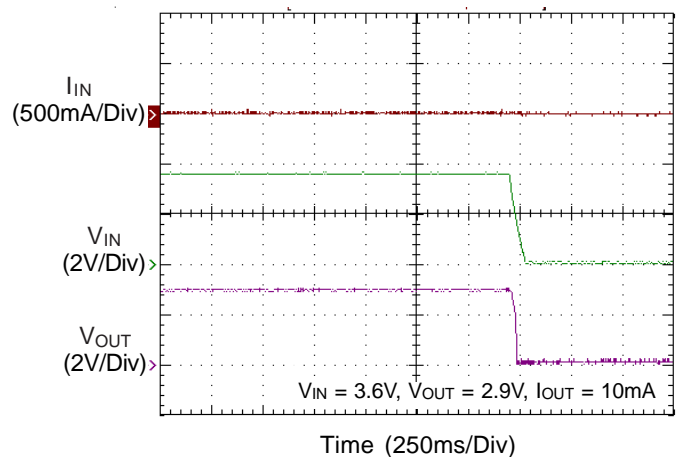
**CH2 Power Off from EN**



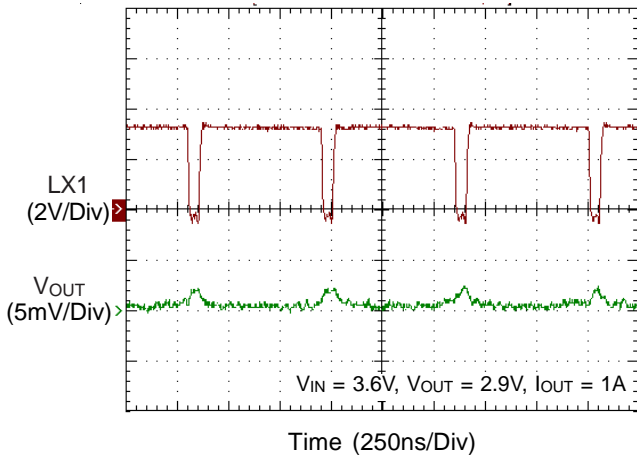
**CH1 Power On from V\_IN**



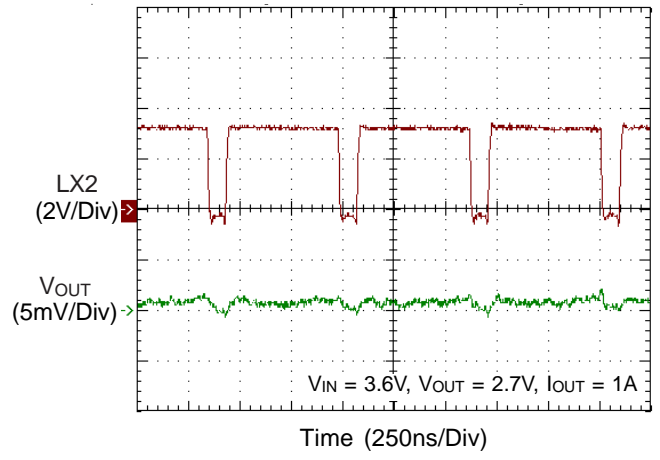
**CH1 Power Off from V\_IN**



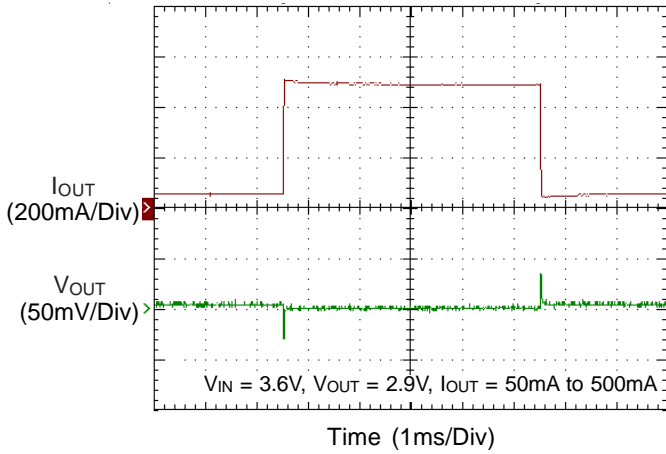
CH1 Output Voltage Ripple



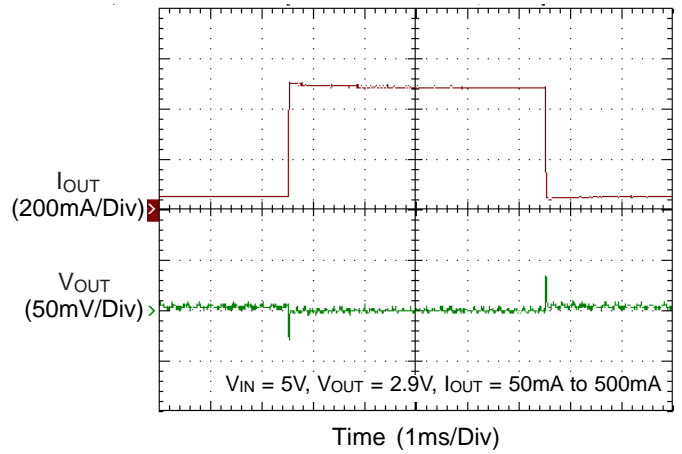
CH2 Output Voltage Ripple



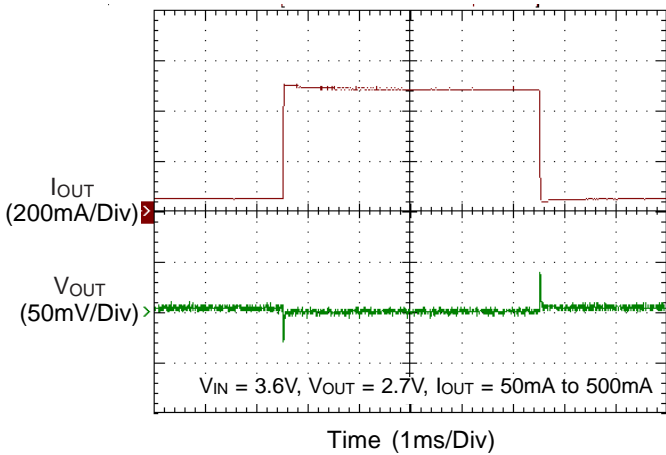
CH1 Load Transient Response



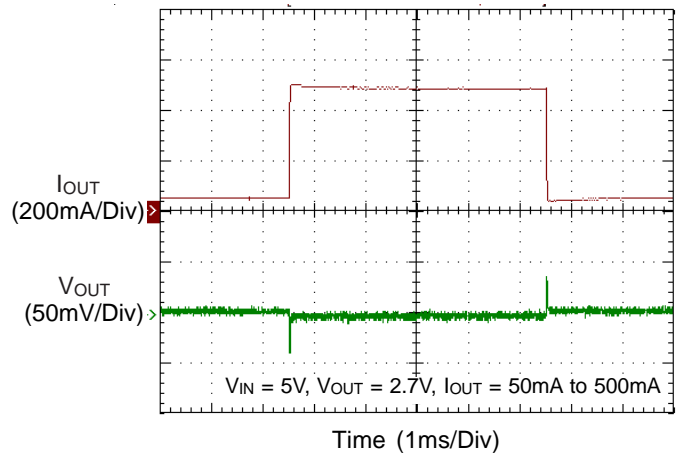
CH1 Load Transient Response



CH2 Load Transient Response



CH2 Load Transient Response



## Applications Information

The basic RT8020H application circuit is shown in Typical Application Circuit. External component selection is determined by the maximum load current and begins with the selection of the inductor value and operating frequency followed by  $C_{IN}$  and  $C_{OUT}$ .

### Inductor Selection

For a given input and output voltage, the inductor value and operating frequency determine the ripple current. The ripple current  $\Delta I_L$  increases with higher  $V_{IN}$  and decreases with higher inductance.

$$\Delta I_L = \left( \frac{V_{OUT}}{f \times L} \right) \times \left( 1 - \frac{V_{OUT}}{V_{IN}} \right)$$

Having a lower ripple current reduces the ESR losses in the output capacitors and the output voltage ripple. Highest efficiency operation is achieved at low frequency with small ripple current. This, however, requires a large inductor.

A reasonable starting point for selecting the ripple current is  $\Delta I_L = 0.4(I_{MAX})$ . The largest ripple current occurs at the highest  $V_{IN}$ . To guarantee that the ripple current stays below a specified maximum, the inductor value should be chosen according to the following equation :

$$L = \left( \frac{V_{OUT}}{f \times \Delta I_L(MAX)} \right) \times \left( 1 - \frac{V_{OUT}}{V_{IN(MAX)}} \right)$$

### Inductor Core Selection

Once the value for L is known, the type of inductor can be selected. High efficiency converters generally cannot afford the core loss found in low cost powdered iron cores, thus, limiting the use to more expensive ferrite or permalloy cores. Actual core loss is independent of core size for a fixed inductor value, but it is very dependent on the inductance selected. As the inductance increases, core losses decrease. However, increased inductance requires more turns of wire and therefore higher copper losses.

Ferrite designs have very low core losses and are preferred at high switching frequencies, thus allowing design goals to concentrate on copper loss and saturation prevention. Ferrite core material saturates "hard", which means that inductance collapses abruptly when the peak design current is exceeded.

This results in an abrupt increase in inductor ripple current and consequent output voltage ripple.

Do not allow the core to saturate!

Different core materials and shapes will change the size/current and price/current relationship of an inductor. Toroid or shielded pot cores in ferrite or permalloy materials are small and don't radiate energy but generally cost more than powdered iron core inductors with similar characteristics. The choice of which type of inductor to use mainly depends on the price vs. size requirements and any radiated field/EMI requirements.

### $C_{IN}$ and $C_{OUT}$ Selection

The input capacitance,  $C_{IN}$ , is needed to filter the trapezoidal current at the source of the top MOSFET. To prevent large ripple voltage, a low ESR input capacitor sized for the maximum RMS current should be used. RMS current is given by :

$$I_{RMS} = I_{OUT(MAX)} \frac{V_{OUT}}{V_{IN}} \sqrt{\frac{V_{IN}}{V_{OUT}} - 1}$$

This formula has a maximum at  $V_{IN} = 2V_{OUT}$ , where  $I_{RMS} = I_{OUT}/2$ . This simple worst-case condition is commonly used for design because even significant deviations do not result in much difference. Note that ripple current ratings from capacitor manufacturers are often based on a life time of only 2000 hours, which makes it advisable to further de-rate the capacitor or choose a capacitor rated at a higher temperature than required. Several capacitors may also be paralleled to meet the size or height requirements in the design.

The selection of  $C_{OUT}$  is determined by the Effective Series Resistance (ESR) that is required to minimize voltage ripple and load step transients, as well as by the amount of bulk capacitance that is necessary to ensure that the control loop is stable. Loop stability can be checked by viewing the load transient response as described in a later section. The output ripple,  $\Delta V_{OUT}$ , is determined by :

$$\Delta V_{OUT} \leq \Delta I_L \left( ESR + \frac{1}{8fC_{OUT}} \right)$$

The output ripple is highest at maximum input voltage since  $\Delta I_L$  increases with input voltage. Multiple capacitors placed in parallel may be needed to meet the ESR and RMS current handling requirements. Dry tantalum, special polymer, aluminum electrolytic and ceramic capacitors are all available in surface mount packages. Special polymer capacitors offer very low ESR, but have lower capacitance density than other types. Tantalum capacitors have the highest capacitance density, but it is important to only use types that have been surge tested for use in switching power supplies. Aluminum electrolytic capacitors have significantly higher ESR, but can be used in cost-sensitive applications provided that consideration is given to ripple current ratings and long-term reliability. Ceramic capacitors have excellent low ESR characteristics, but can have a high voltage coefficient and audible piezoelectric effects. The high Q of ceramic capacitors with trace inductance can also lead to significant ringing.

### Using Ceramic Input and Output Capacitors

Higher value, lower cost ceramic capacitors are now becoming available in smaller case sizes. Their high ripple current, high voltage rating and low ESR make them ideal for switching regulator applications. However, care must be taken when these capacitors are used at the input and output. When a ceramic capacitor is used at the input and the power is supplied by a wall adapter through long wires, a load step at the output can induce ringing at the input,  $V_{IN}$ . At best, this ringing can couple to the output and be mistaken as loop instability. At worst, a sudden inrush of current through the long wires can potentially cause a voltage spike at  $V_{IN}$  large enough to damage the part.

### Efficiency Considerations

The efficiency of a switching regulator is equal to the output power divided by the input power times 100%. It is often useful to analyze individual losses to determine what is limiting the efficiency and which change would produce the most improvement. Efficiency can be expressed as :

$$\text{Efficiency} = 100\% - (L1 + L2 + L3 + \dots)$$

where L1, L2, etc. are the individual losses as a percentage of input power. Although all dissipative elements in the circuit produce losses, two main sources usually account

for most of the losses :  $V_{IN}$  quiescent current and  $I^2R$  losses.

The  $V_{IN}$  quiescent current loss dominates the efficiency loss at very low load currents whereas the  $I^2R$  loss dominates the efficiency loss at medium to high load currents. In a typical efficiency plot, the efficiency curve at very low load currents can be misleading since the actual power lost is of no consequence.

1. The  $V_{IN}$  quiescent current appears due to two components : the DC bias current and the gate charge currents. The gate charge current results from switching the gate capacitance of the internal power MOSFET switches. Each time the gate is switched from high to low to high again, a packet of charge  $\Delta Q$  moves from  $V_{IN}$  to ground.

The resulting  $\Delta Q/\Delta t$  is the current out of  $V_{IN}$  that is typically larger than the DC bias current. In continuous mode,

$$I_{\text{GATECHG}} = f(Q_T + Q_B)$$

where  $Q_T$  and  $Q_B$  are the gate charges of the internal top and bottom switches. Both the DC bias and gate charge losses are proportional to  $V_{IN}$  and thus their effects will be more pronounced at higher supply voltages.

2.  $I^2R$  losses are calculated from the resistances of the internal switches,  $R_{SW}$  and external inductor,  $R_L$ . In continuous mode the average output current flowing through inductor L is "chopped" between the main switch and the synchronous switch. Thus, the series resistance looking into the LX pin is a function of both top and bottom MOSFET  $R_{DS(ON)}$  as well as the duty cycle (DC). The equation is shown below :

$$R_{SW} = R_{DS(ON)TOP} \times DC + R_{DS(ON)BOT} \times (1 - DC)$$

The  $R_{DS(ON)}$  for both the top and bottom MOSFETs can be obtained from the Typical Performance Characteristics curves. Thus, to obtain  $I^2R$  losses, simply add  $R_{SW}$  to  $R_L$  and multiply the result by the square of the average output current. Other losses including  $C_{IN}$  and  $C_{OUT}$  ESR dissipative losses and inductor core losses generally account for less than 2% of the total loss.

### Checking Transient Response

The regulator loop response can be checked by looking at the load transient response. Switching regulators take

several cycles to respond to a step in load current. When a load step occurs,  $V_{OUT}$  immediately shifts by an amount equal to  $\Delta I_{LOAD}$  (ESR), where ESR is the effective series resistance of  $C_{OUT}$ .  $\Delta I_{LOAD}$  also begins to charge or discharge  $C_{OUT}$ , generating a feedback error signal used by the regulator to return  $V_{OUT}$  to its steady-state value. During this recovery time,  $V_{OUT}$  can be monitored for overshoot or ringing which would indicate a stability problem.

**Thermal Considerations**

The maximum power dissipation depends on the thermal resistance of IC package, PCB layout, rate of surrounding airflow, and difference between junction and ambient temperature. The maximum power dissipation can be calculated by the following formula :

$$P_{D(MAX)} = ( T_{J(MAX)} - T_A ) / \theta_{JA}$$

where  $T_{J(MAX)}$  is the maximum junction temperature,  $T_A$  is the ambient temperature and  $\theta_{JA}$  is the junction to ambient thermal resistance. For recommended operating conditions specification of the RT8020H DC/DC converter,  $T_{J(MAX)}$  is the maximum junction temperature of the die and  $T_A$  is the ambient temperature. The junction to ambient thermal resistance  $\theta_{JA}$  is layout dependent. For WDFN-12L 3x3 packages, the thermal resistance,  $\theta_{JA}$ , is 60°C/W on a standard JEDEC 51-7 four-layer thermal test board. The maximum power dissipation at  $T_A = 25^\circ\text{C}$  can be calculated by the following formula :

$$P_{D(MAX)} = ( 125^\circ\text{C} - 25^\circ\text{C} ) / ( 60^\circ\text{C/W} ) = 1.667\text{W for WDFN-12L 3x3 package}$$

The maximum power dissipation depends on the operating ambient temperature for fixed  $T_{J(MAX)}$  and thermal resistance,  $\theta_{JA}$ . For the RT8020H package, the derating curves in Figure 1 allows the designer to see the effect of rising ambient temperature on the maximum power dissipation.

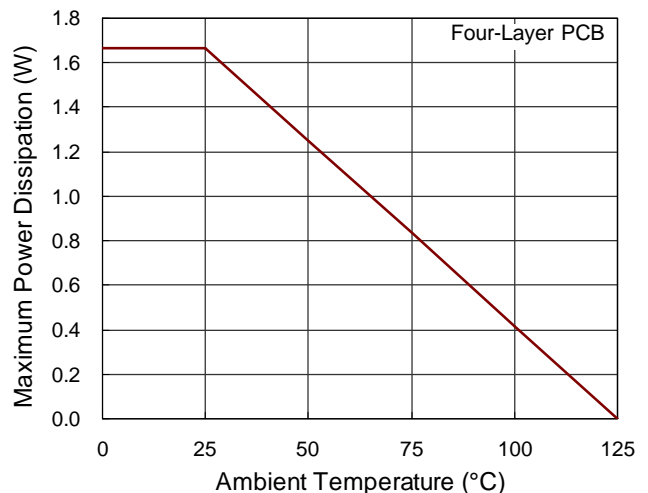


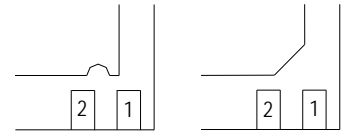
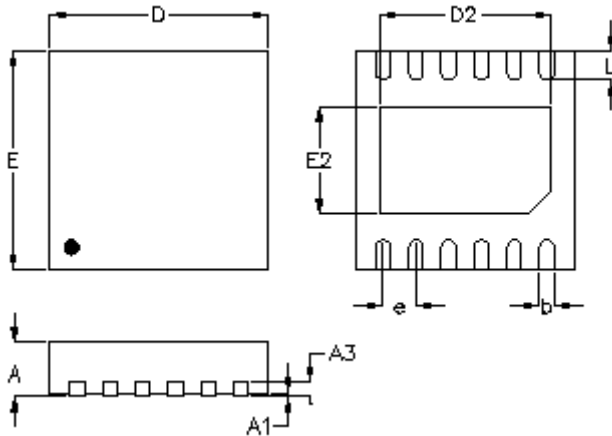
Figure 1. Derating Curve for RT8020H Package

**Layout Considerations**

Follow the PCB layout guidelines for optimal performance of the RT8020H.

- ▶ For the main current paths, keep their traces short and wide.
- ▶ Place the input capacitor as close as possible to the device pins (VIN and GND).
- ▶ LX node experiences high frequency voltage swing and should be kept in a small area. Keep analog components away from LX node to prevent stray capacitive noise pick-up.
- ▶ Connect feedback network behind the output capacitors. Keep the loop area small. Place the feedback components near the RT8020H.
- ▶ Connect all analog grounds to a command node and then connect the command node to the power ground behind the output capacitors.

## Outline Dimension



### DETAILA

Pin #1 ID and Tie Bar Mark Options

Note : The configuration of the Pin #1 identifier is optional, but must be located within the zone indicated.

Symbol	Dimensions In Millimeters		Dimensions In Inches		
	Min.	Max.	Min.	Max.	
A	0.700	0.800	0.028	0.031	
A1	0.000	0.050	0.000	0.002	
A3	0.175	0.250	0.007	0.010	
b	0.150	0.250	0.006	0.010	
D	2.950	3.050	0.116	0.120	
D2	Option1	2.300	2.650	0.091	0.104
	Option2	1.970	2.070	0.078	0.081
E	2.950	3.050	0.116	0.120	
E2	Option1	1.400	1.750	0.055	0.069
	Option2	1.160	1.260	0.046	0.050
e	0.450		0.018		
L	0.350	0.450	0.014	0.018	

### W-Type 12L DFN 3x3 Package

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