

# Dual-Channel Synchronous DC-DC Step-Down Controller with 5V/3.3V LDOs

## General Description

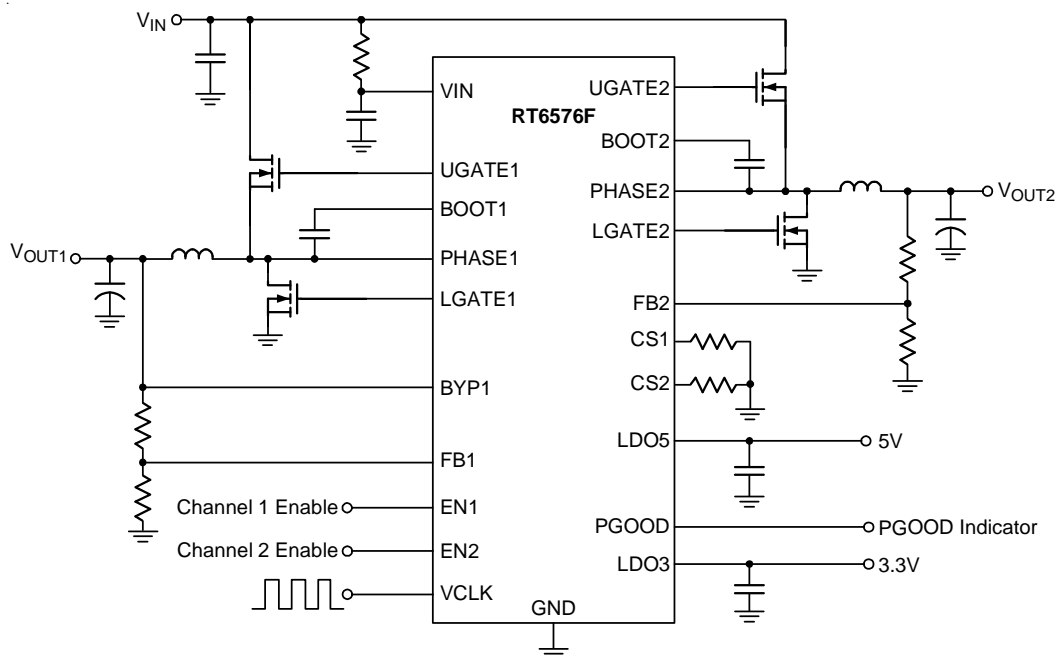
The RT6576F is a dual-channel step-down controller generating supply voltages for battery-powered systems. It includes two Pulse-Width Modulation (PWM) controllers adjustable from 2V to 5.5V, and two fixed 5V/3.3V linear regulators. Each linear regulator provides up to 100mA output current and 3.3V linear regulator provides 1% accuracy under 35mA. The RT6576F has an oscillator output to drive the external charge pump application. Other features include on-board power-up sequencing, a power-good output, internal soft-start, and soft-discharge output that prevents negative voltage during shutdown.

A constant current ripple PWM control scheme operates without sense resistors and provides 100ns response to load transient. For maximizing power efficiency, the RT6576F automatically switches to the diode-emulation mode in light load applications. To eliminate noise in audio applications, an audio-skipping mode is included, which maintains the switching frequency above 25kHz. The RT6576F is available in the WQFN-20L 3x3 package.

## Features

- Support Connected Standby Mode for Ultrabook
- CCRCOT Control with 100ns Load Step Response
- PWM Maximum Duty Ratio > 98%
- 5V to 25V Input Voltage Range
- Dual Adjustable Output :
  - ▶ CH1 : 2V to 5.5V
  - ▶ CH2 : 2V to 4V
- 5V/3.3V LDOs with 100mA Output Current
- 1% Accuracy on 3.3V LDO Output
- Oscillator Driving Output for Charge Pump Application
- Support Audio-Skipping Mode (ASM)
- Internal Frequency Setting
  - ▶ 300kHz/355kHz (CH1/CH2)
- Internal Soft-Start and Soft-Discharge
- 4700ppm/°C  $R_{DS(ON)}$  Current Sensing
- Independent Switcher Enable Control
- Built-In OVP/UVP/OCP/OTP
- Non-Latch UVLO
- Power Good Indicator

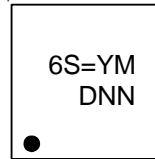
## Simplified Application Circuit



## Applications

- Notebook and Sub-Notebook Computers
- System Power Supplies
- 2-Cell to 4-Cell Li+ Battery-Powered Devices

## Marking Information



6S= : Product Code  
YMDNN : Date Code

## Ordering Information

RT6576F □ □ □

- Pin 1 Orientation\*\*\*  
(2) : Quadrant 2, Follow EIA-481-D
- Package Type  
QW : WQFN-20L 3x3 (W-Type)
- Lead Plating System  
G : Green (Halogen Free and Pb Free)

Note :

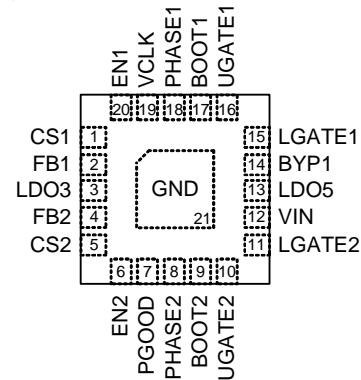
\*\*\*Empty means Pin1 orientation is Quadrant 1

Richtek products are :

- ▶ RoHS compliant and compatible with the current requirements of IPC/JEDEC J-STD-020.
- ▶ Suitable for use in SnPb or Pb-free soldering processes.

## Pin Configuration

(TOP VIEW)



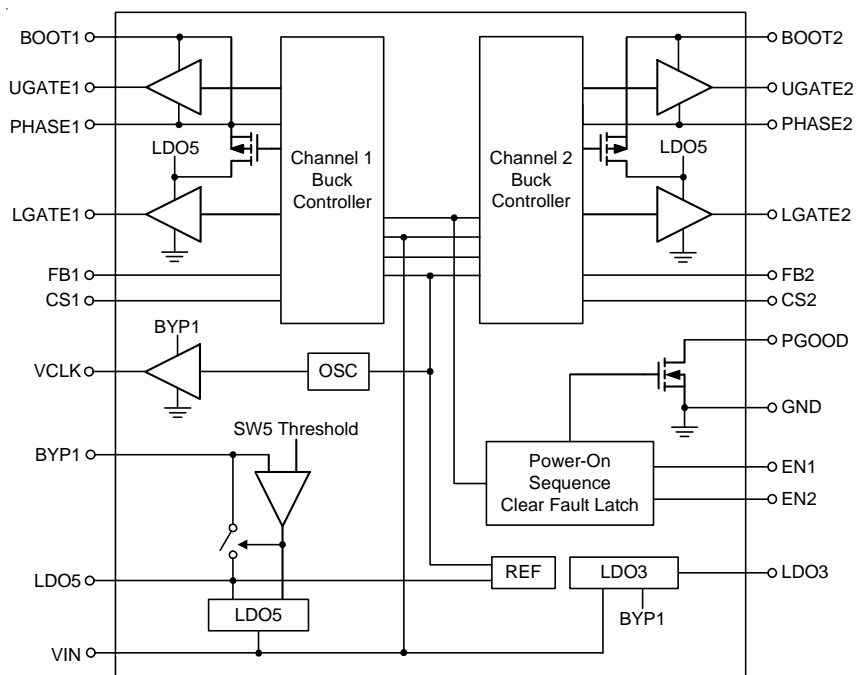
WQFN-20L 3x3

## Functional Pin Description

Pin No.	Pin Name	Pin Function
1	CS1	Current limit setting. Connect a resistor to GND to set the threshold for Channel 1 synchronous $R_{DS(ON)}$ sense. The GND – PHASE1 current limit threshold is 1/8th the voltage seen at CS1 over a 0.2V to 2V range. There is an internal 10 $\mu$ A current source from LDO5 to CS1.
2	FB1	Feedback voltage input for channel 1. Connect FB1 to a resistive voltage divider from VOUT1 to GND to adjust output from 2V to 5.5V.
3	LDO3	3.3V linear regulator output. It is always on when VIN is higher than VINPOR threshold.
4	FB2	Feedback voltage input for channel 2. Connect FB2 to a resistive voltage divider from VOUT2 to GND to adjust output from 2V to 4V.
5	CS2	Current limit setting. Connect a resistor to GND to set the threshold for channel 2 synchronous $R_{DS(ON)}$ sense. The GND – PHASE2 current limit threshold is 1/8th the voltage seen at CS2 over a 0.2V to 2V range. There is an internal 10 $\mu$ A current source from LDO5 to CS2.
6	EN2	Enable control input for Channel 2.
7	PGOOD	Power good indicator output for channel 1 and channel 2. (Logical AND)
8	PHASE2	Switch node of channel 2 MOSFETs. PHASE2 is the internal lower supply rail for the UGATE2 high-side gate driver. PHASE2 is also the current-sense input for the channel 2.

Pin No.	Pin Name	Pin Function
9	BOOT2	Bootstrap supply for channel 2 high-side gate driver. Connect to an external capacitor according to the typical application circuits.
10	UGATE2	High-side gate driver output for channel 2. UGATE2 swings between PHASE2 and BOOT2.
11	LGATE2	Low-Side gate driver output for channel 2. LGATE2 swings between GND and LDO5.
12	VIN	Power input for 5V and 3.3V LDO regulators and buck controllers.
13	LDO5	5V linear regulator output. LDO5 is also the supply voltage for the low-side MOSFET and analog supply voltage for the device.
14	BYP1	Switch-over source voltage input for LDO5.
15	LGATE1	Low-side gate driver output for channel 1. LGATE1 swings between GND and LDO5.
16	UGATE1	High-side gate driver output for channel 1. UGATE1 swings between PHASE1 and BOOT1.
17	BOOT1	Bootstrap supply for channel 1 high-side gate driver. Connect to an external capacitor according to the typical application circuits.
18	PHASE1	Switch node of channel 1 MOSFETs. PHASE1 is the internal lower supply rail for the UGATE1 high-side gate driver. PHASE1 is also the current sense input for the channel 1.
19	VCLK	Oscillator output for charge pump.
20	EN1	Enable control input for channel 1.
21 (Exposed Pad)	GND	Ground. The exposed pad must be soldered to a large PCB and connected to GND for maximum power dissipation.

**Functional Block Diagram**



## Operation

The RT6576F includes two constant on-time synchronous step-down controllers and two linear regulators.

### Buck Controller

In normal operation, the high-side N-MOSFET is turned on when the output is lower than VREF, and is turned off after the internal one-shot timer expires. While the high-side N-MOSFET is turned off, the low-side N-MOSFET is turned on to conduct the inductor current until next cycle begins.

### Soft-Start

For internal soft-start function, an internal current source charges an internal capacitor to build the soft-start ramp voltage. The output voltage will track the internal ramp voltage during soft-start interval.

### PGOOD

The power good output is an open-drain architecture. When the two channels soft-start are both finished, the PGOOD open-drain output will be high impedance.

### Current Limit

The current limit circuit employs a unique "valley" current sensing algorithm. If the magnitude of the current sense signal at PHASE is above the current limit threshold, the PWM is not allowed to initiate a new cycle. Thus, the current to the load exceeds the average output inductor current, the output voltage falls and eventually crosses the under-voltage protection threshold, inducing IC shutdown.

### Over-Voltage Protection (OVP) & Under-Voltage Protection (UVP)

The two channel output voltages are continuously monitored for over-voltage and under-voltage conditions. When the output voltage exceeds over-voltage threshold (113% of VOUT), UGATE goes low and LGATE is forced high. When it is less than 52% of reference voltage, under-voltage protection is triggered and then both UGATE and LGATE gate drivers are forced low. The controller is latched until ENx is reset or LDO5 is re-supplied.

### LDO5 and LDO3

When the VIN voltage exceeds the POR rising threshold, LDO3 and LDO5 will default turn-on. The linear regulator LDO5 and LDO3 provide 5V and 3.3V regulated output.

### Switching Over

The BYP1 is connected to the Channel 1 output. After the Channel 1 output voltage exceeds the set threshold (4.66V), the output will be bypassed to the LDO5 output to maximize the efficiency.

**Absolute Maximum Ratings** (Note 1)

• VIN to GND -----	-0.3V to 30V
• BOOTx to GND	
DC -----	-0.3V to 36V
<100ns -----	-5V to 42V
• BOOTx to PHASEx	
DC -----	-0.3V to 6V
<100ns -----	-5V to 7.5V
• PHASEx to GND	
DC -----	-5V to 30V
<100ns -----	-10V to 42V
• UGATEx to GND	
DC -----	-5V to 36V
<100ns -----	-10V to 42V
• UGATEx to PHASEx	
DC -----	-0.3V to 6V
<100ns -----	-5V to 7.5V
• LGATEx to GND	
DC -----	-0.3V to 6V
<100ns -----	-5V to 7.5V
• Other Pins -----	-0.3V to 6.5V
• Power Dissipation, P <sub>D</sub> @ T <sub>A</sub> = 25°C	
WQFN-20L 3x3 -----	3.33W
• Package Thermal Resistance (Note 2)	
WQFN-20L 3x3, θ <sub>JA</sub> -----	30°C/W
WQFN-20L 3x3, θ <sub>JC</sub> -----	7.5°C/W
• Junction Temperature -----	150°C
• Lead Temperature (Soldering, 10 sec.) -----	260°C
• Storage Temperature Range -----	-65°C to 150°C
• ESD Susceptibility (Note 3)	
HBM (Human Body Model) -----	2kV

**Recommended Operating Conditions** (Note 4)

• Supply Voltage, VIN -----	5V to 25V
• Junction Temperature Range -----	-40°C to 125°C
• Ambient Temperature Range -----	-40°C to 85°C

## Electrical Characteristics

( $V_{IN} = 12V$ ,  $V_{EN1} = V_{EN2} = 3.3V$ ,  $V_{CS1} = V_{CS2} = 2V$ , No Load,  $T_A = 25^{\circ}C$ , unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
<b>Input Supply</b>						
VIN Power-On Reset	VINPOR	Rising threshold	--	4.6	4.9	V
		Falling threshold	3.2	3.7	--	
VIN Standby Supply Current	IVIN_SBY	Both buck controllers off, $V_{EN1} = V_{EN2} = GND$	--	80	100	$\mu A$
VIN Quiescent Current	IVIN_nosw	Both buck controllers on, $V_{FBx} = 2.05V$ , $V_{BYP1} = 5.05V$	--	15	25	$\mu A$
BYP1 Supply Current	IBYP1_nosw	Both buck controllers on, $V_{FBx} = 2.05V$ , $V_{BYP1} = 5.05V$	--	420	500	$\mu A$
<b>Buck Controllers Output and FB Voltage</b>						
FBx Valley Trip Voltage	VFBx	CCM operation	1.98	2	2.02	V
BYP1 Discharge Current	IDCHG_BYP1	$V_{BYP1} = 0.5V$	10	45	--	mA
PHASEx Discharge Current	IDCHG_LX	$V_{PHASEx} = 0.5V$	5	8	--	mA
<b>Switching Frequency</b>						
Switching Frequency	fswx	$V_{IN} = 20V$ , $V_{OUT1} = 5V$	240	300	360	kHz
		$V_{IN} = 20V$ , $V_{OUT2} = 3.33V$	280	355	430	
Minimum Off-Time	toff_MIN	$V_{FBx} = 1.9V$	--	200	275	ns
<b>Soft-Start</b>						
Soft-Start Time	tssx	$V_{OUTx}$ ramp-up time	2	--	4.5	ms
<b>Current Sense</b>						
CSx Source Current	ICSx	$V_{CSx} = 1V$ , $V_{FBx} = 1.9V$	9	10	11	$\mu A$
CSx Current Temperature Coefficient	TCICSx	In Comparison with $25^{\circ}C$	--	4700	--	ppm/ $^{\circ}C$
Zero-Current Threshold	VZC	$V_{FBx} = 2.05V$ , GND – PHASEx	--	1	--	mV
<b>Internal Regulator</b>						
LDO5 Output Voltage	VLDO5	$V_{IN} = 12V$ , no load	4.9	5	5.1	V
		$V_{IN} > 7V$ , $I_{LDO5} < 100mA$	4.8	5	5.1	
		$V_{IN} > 5.5V$ , $I_{LDO5} < 35mA$	4.8	5	5.1	
		$V_{IN} > 5V$ , $I_{LDO5} < 20mA$	4.5	4.75	5.1	
LDO3 Output Voltage	VLDO3	$V_{IN} = 12V$ , no load	3.267	3.3	3.333	V
		$V_{IN} > 7V$ , $I_{LDO3} < 100mA$	3.217	3.3	3.383	
		$V_{IN} > 5.5V$ , $I_{LDO3} < 35mA$	3.267	3.3	3.333	
		$V_{IN} > 5V$ , $I_{LDO3} < 20mA$	3.217	3.3	3.383	

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit	
LDO5 Output Current	I <sub>LDO5</sub>	V <sub>LDO5</sub> = 4.5V, V <sub>BYP1</sub> = GND, V <sub>IN</sub> = 7.4V	100	175	--	mA	
LDO3 Output Current	I <sub>LDO3</sub>	V <sub>LDO3</sub> = 3V, V <sub>IN</sub> = 7.4V	100	175	--	mA	
LDO5 Switch-Over Threshold to BYP1	V <sub>SWTH</sub>	Rising edge at BYP1 regulation point	--	4.66	--	V	
LDO5 Switch-over Equivalent Resistance	R <sub>SW</sub>	LDO5 to BYP1, 10mA	--	1.5	3	Ω	
<b>VCLK Output</b>							
VCLK On-Resistance	R <sub>VCLK</sub>	Pull-up and pull-down resistance	--	10	--	Ω	
VCLK Switching Frequency	f <sub>VCLK</sub>		--	260	--	kHz	
<b>UVLO</b>							
LDO5 UVLO Threshold	V <sub>UVLO5</sub>	Rising edge	--	4.3	4.6	V	
		Falling edge	3.7	3.9	4.1		
LDO3 UVLO Threshold	V <sub>UVLO3</sub>	Channel x off	--	2.5	--	V	
<b>Power Good Indicator</b>							
PGOOD Threshold	V <sub>PGxTH</sub>	PGOOD detect, V <sub>FBx</sub> rising edge	84	88	92	%	
		Hysteresis	--	8	--		
PGOOD Leakage Current		High state, V <sub>PGOOD</sub> = 5.5V	--	--	1	μA	
PGOOD Output Low Voltage		I <sub>SINK</sub> = 4mA	--	--	0.3	V	
<b>Fault Detection</b>							
OVP Trip Threshold	V <sub>OVP</sub>	FBx with respect to internal reference	109	113	117	%	
OVP Propagation Delay			--	1	--	μs	
UVP Trip Threshold	V <sub>UVP</sub>	UVP detect, FBx falling edge	47	52	57	%	
UVP Shutdown Blanking Time	t <sub>SHDN_UVP</sub>	From ENx enable	--	4.5	--	ms	
<b>Thermal Shutdown</b>							
Thermal Shutdown	T <sub>SD</sub>		--	150	--	°C	
Thermal Shutdown Hysteresis	ΔT <sub>SD</sub>		--	10	--	°C	
<b>Logic Inputs</b>							
ENx Threshold Voltage	Logic-High	V <sub>ENx_H</sub>	SMPS on	1.6	--	--	V
	Logic-Low	V <sub>ENx_L</sub>	SMPS off	--	--	0.4	
<b>Internal Boost Switch</b>							
Internal Boost Switch On-Resistance	R <sub>BST</sub>	LDO5 to BOOTx	--	80	--	Ω	

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
<b>Power MOSFET Drivers</b>						
UGATE <sub>x</sub> On-Resistance	R <sub>UGATE<sub>x</sub></sub>	High state, V <sub>BOOT<sub>x</sub></sub> – V <sub>UGATE<sub>x</sub></sub> = 0.25V, V <sub>BOOT<sub>x</sub></sub> – V <sub>PHASE<sub>x</sub></sub> = 5V	--	3	--	Ω
		Low state, V <sub>UGATE<sub>x</sub></sub> – V <sub>PHASE<sub>x</sub></sub> = 0.25V, V <sub>BOOT<sub>x</sub></sub> – V <sub>PHASE<sub>x</sub></sub> = 5V	--	2	--	
LGATE <sub>x</sub> On-Resistance	R <sub>LGATE<sub>x</sub></sub>	High state, V <sub>LDO5</sub> – V <sub>LGATE<sub>x</sub></sub> = 0.25V, V <sub>LDO5</sub> = 5V	--	3	--	Ω
		Low state, V <sub>LGATE<sub>x</sub></sub> – GND = 0.25V	--	1	--	
Dead-Time	t <sub>D</sub>	LGATE <sub>x</sub> rising	--	20	--	ns
		UGATE <sub>x</sub> rising	--	30	--	

**Note 1.** Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions may affect device reliability.

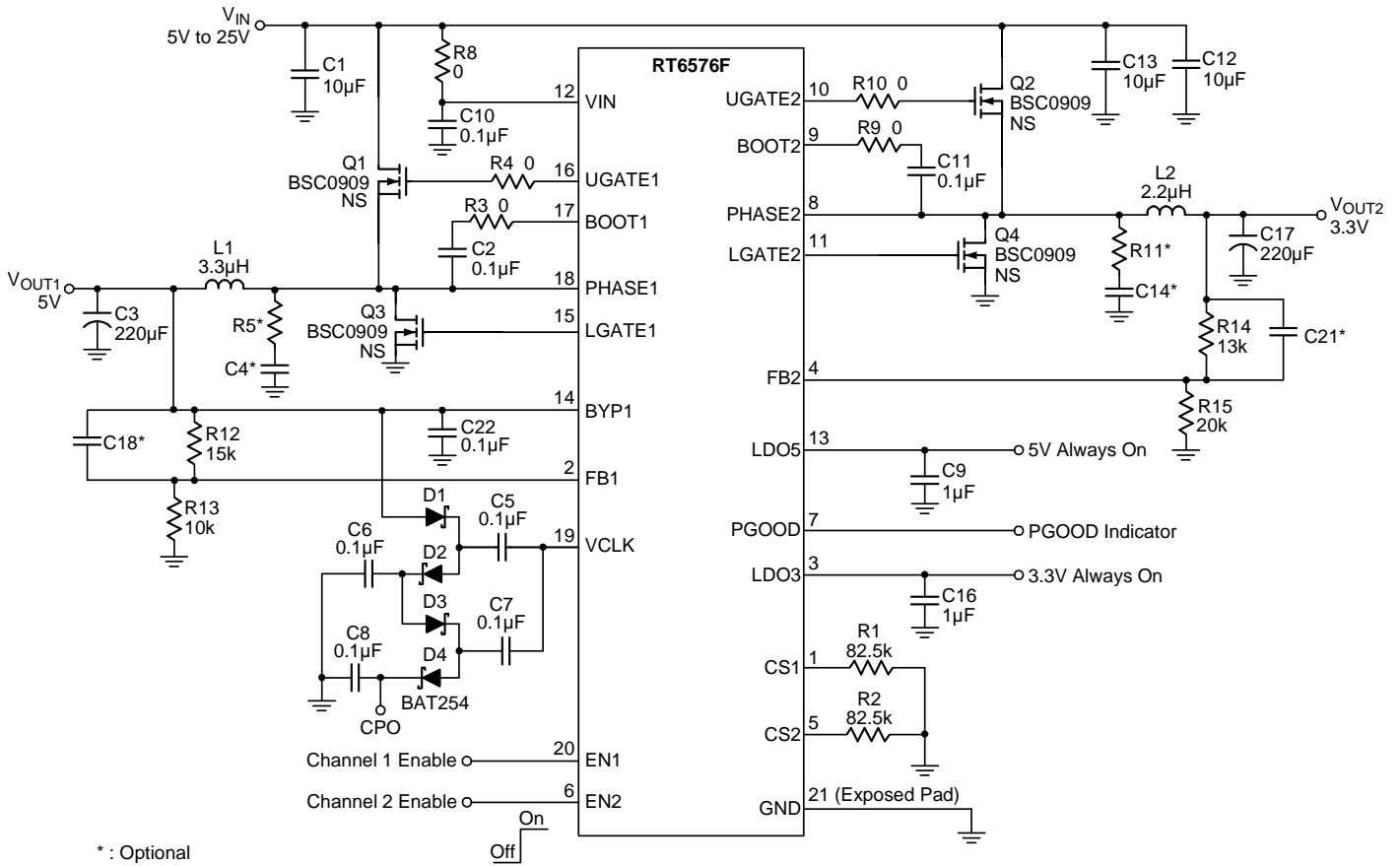
**Note 2.** θ<sub>JA</sub> is measured under natural convection (still air) at T<sub>A</sub> = 25°C with the component mounted on a high effective-thermal-conductivity four-layer test board on a JEDEC 51-7 thermal measurement standard. θ<sub>JC</sub> is measured at the exposed pad of the package.

**Note 3.** Devices are ESD sensitive. Handling precautions are recommended.

**Note 4.** The device is not guaranteed to function outside its operating conditions.

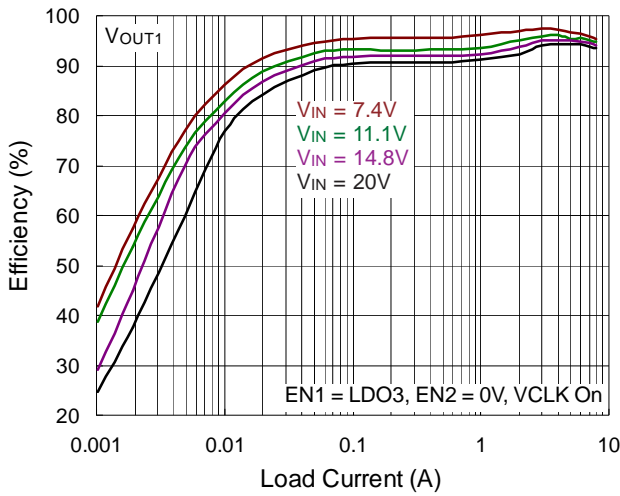


**Typical Application Circuit**

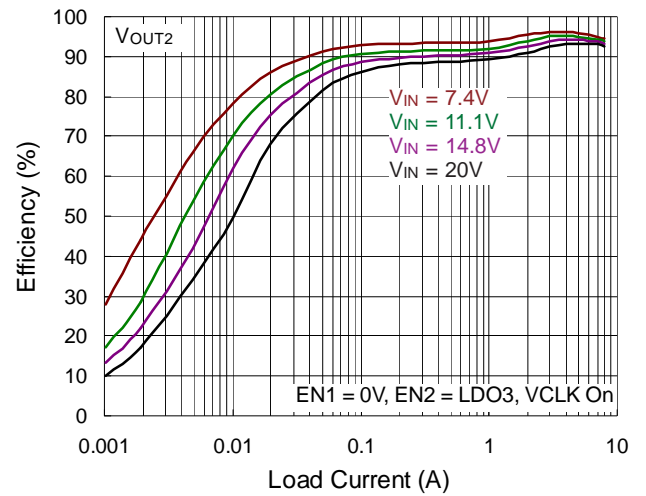


Typical Operating Characteristics

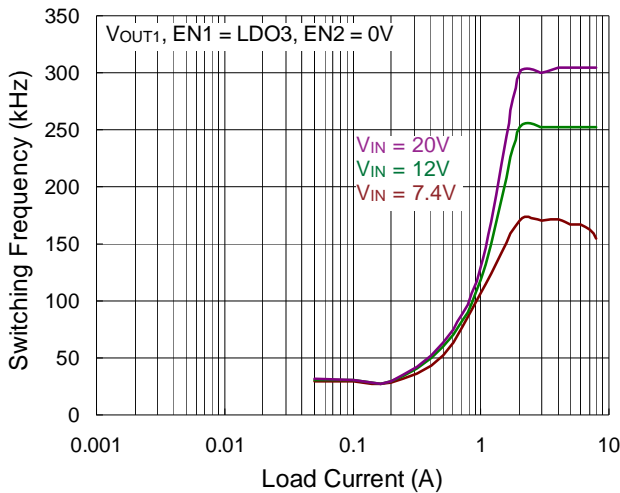
Efficiency vs. Load Current



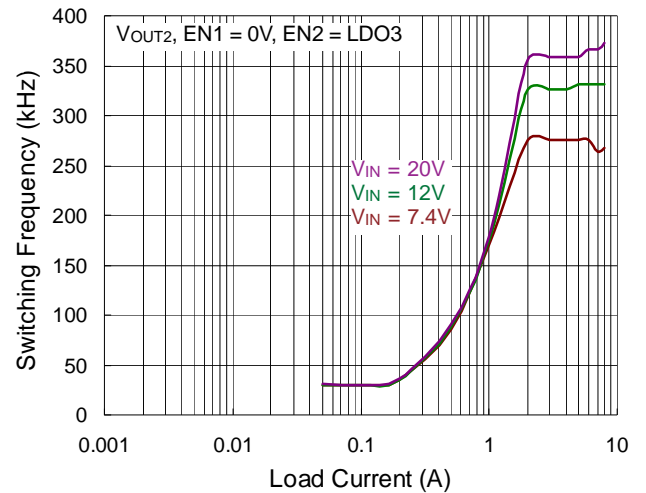
Efficiency vs. Load Current



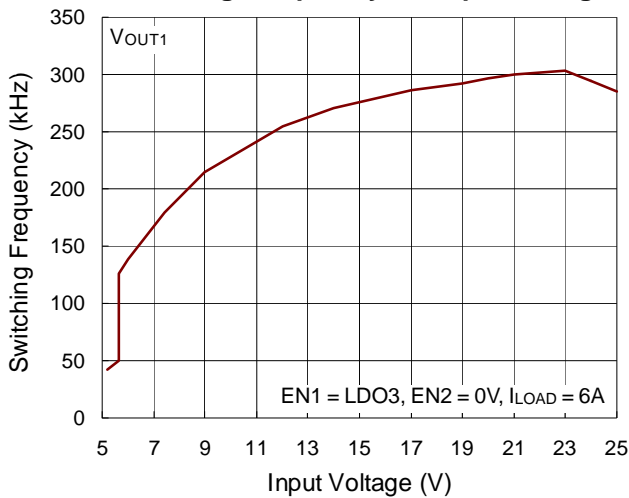
Switching Frequency vs. Load Current



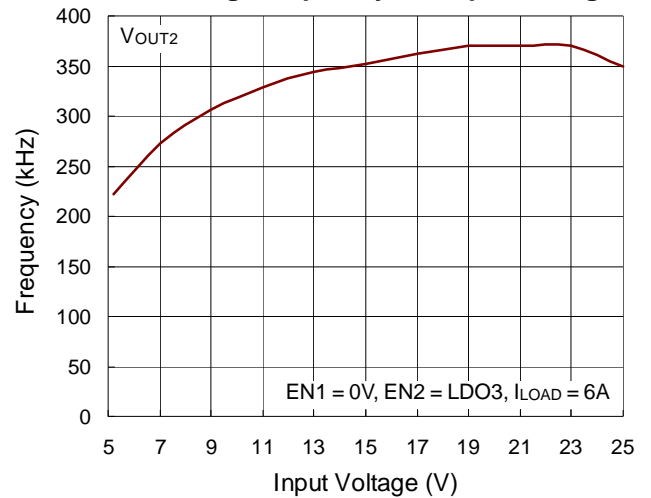
Switching Frequency vs. Load Current



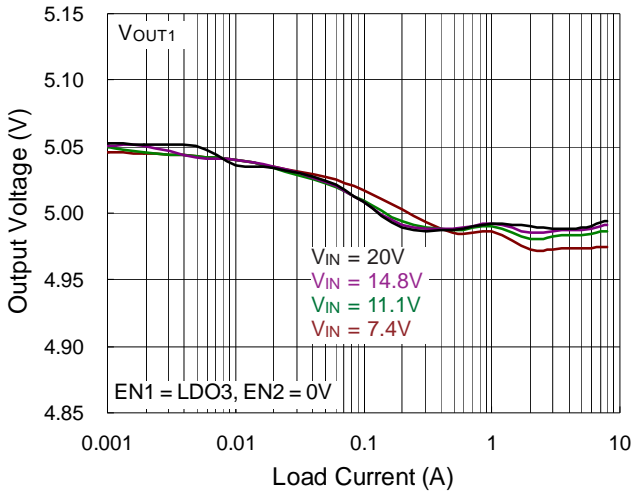
Switching Frequency vs. Input Voltage



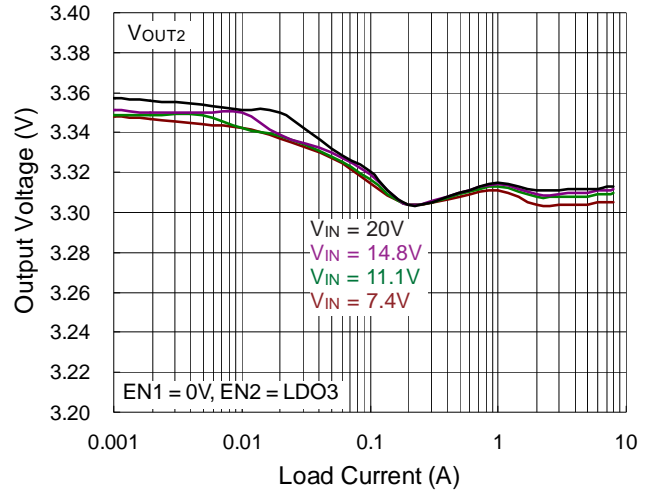
Switching Frequency vs. Input Voltage



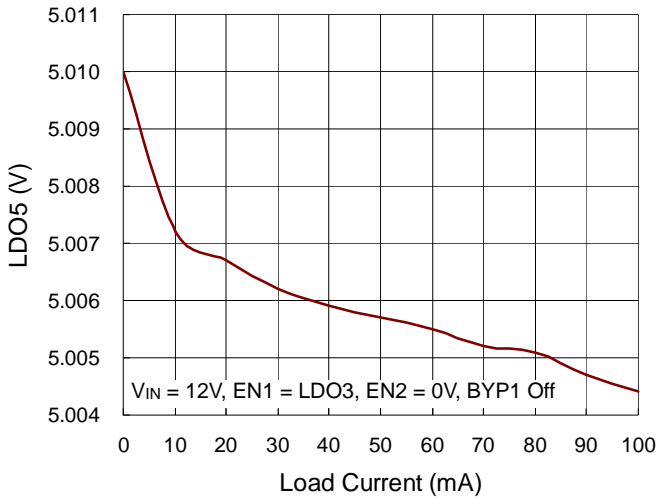
Output Voltage vs. Load Current



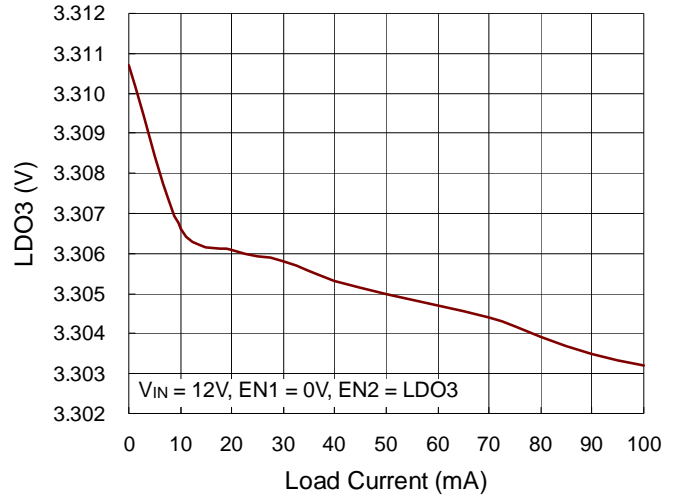
Output Voltage vs. Load Current



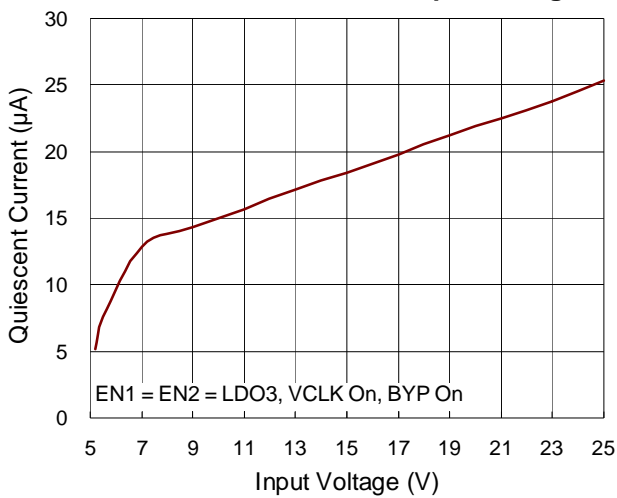
LDO5 vs. Load Current



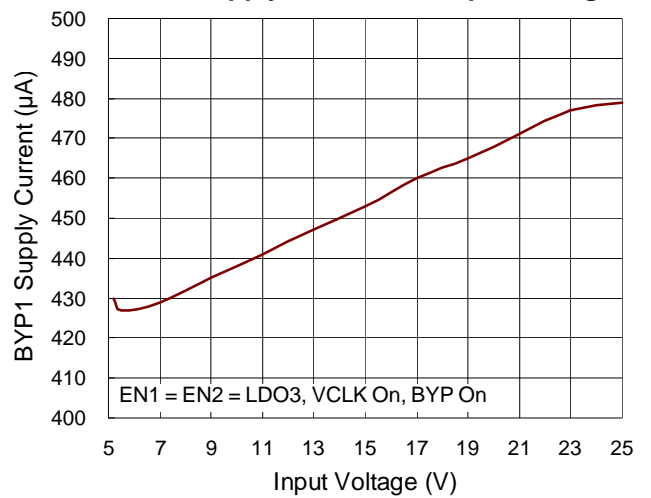
LDO3 vs. Load Current



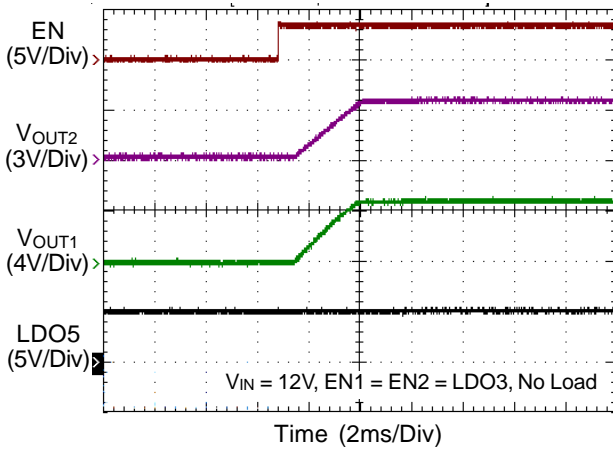
Quiescent Current vs. Input Voltage



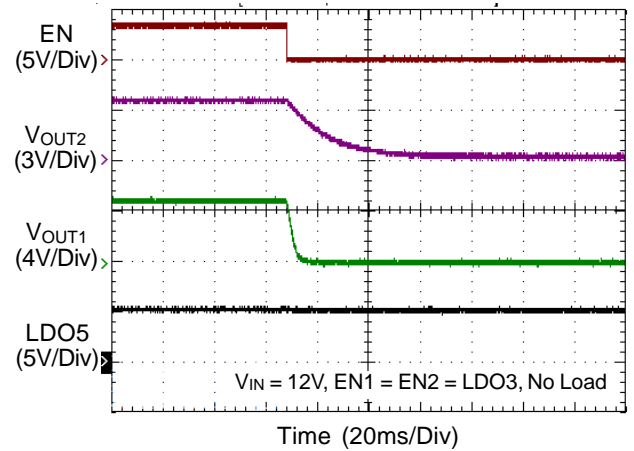
BYP1 Supply Current vs. Input Voltage



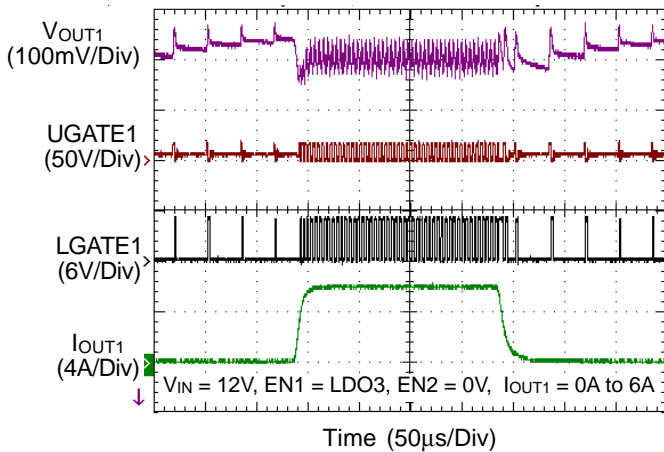
Power On from EN



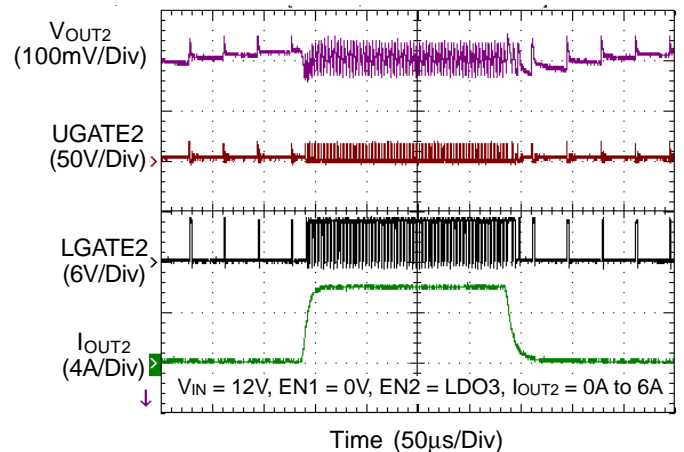
Power Off from EN



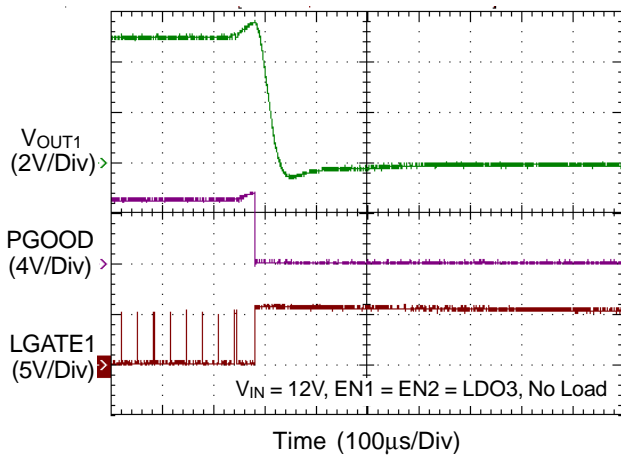
VOUT1 Load Transient Response



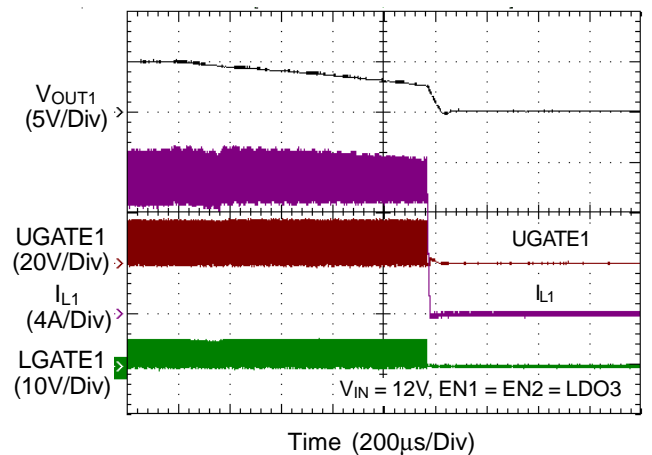
VOUT2 Load Transient Response



OVP



UVP



## Application Information

The RT6576F is a dual-channel, low quiescent, Mach Response™ DRV™ mode synchronous Buck controller targeted for Ultrabook system power supply solutions. Richtek's Mach Response™ technology provides fast response to load steps. The topology solves the poor load transient response timing problems of fixed frequency current mode PWMs, and avoids the problems caused by widely varying switching frequencies in CCR (constant current ripple) constant on-time and constant off-time PWM schemes. A special adaptive on-time control trades off the performance and efficiency over wide input voltage range. The RT6576F includes 5V (LDO5) and 3.3V (LDO3) linear regulators. The LDO5 linear regulator steps down the battery voltage to supply both internal circuitry and gate drivers. The synchronous switch gate drivers are directly powered by LDO5. When V<sub>OUT1</sub> rises above 4.66V, an automatic circuit disconnects the linear regulator and allows the device to be powered by V<sub>OUT1</sub> via the BYP1 pin.

### PWM Operation

The Mach Response™ DRV™ mode controller relies on the output filter capacitor's Effective Series Resistance (ESR) to act as a current sense resistor, so that the output ripple voltage provides the PWM ramp signal. Referring to the RT6576F's Function Block Diagram, the synchronous high-side MOSFET is turned on at the beginning of each cycle. After the internal one-shot timer expires, the MOSFET will be turned off. The pulse width of this one-shot is determined by the converter's input output voltages to keep the frequency fairly constant over the entire input voltage range. Another one-shot sets a minimum off-time (200ns typ.). The on-time one-shot will be triggered if the error comparator is high, the low-side switch current is below the current limit threshold, and the minimum off-time one-shot has timed out.

### PWM Frequency and On-Time Control

For each specific input voltage range, the Mach Response™ control architecture runs with pseudo constant frequency by feed forwarding the input and output voltage into the on-time one-shot timer. The high-side switch

on-time is inversely proportional to the input voltage as measured by V<sub>IN</sub> and proportional to the output voltage. The inductor ripple current operating point remains relatively constant, resulting in easy design methodology and predictable output voltage ripple. The frequency of 3V output controller is set higher than the frequency of 5V output controller. This is done to prevent audio frequency "beating" between the two sides, which switch asynchronously for each side.

The RT6576F adaptively changes the operation frequency according to the input voltage. Higher input voltage usually comes from an external adapter, so the RT6576F operates with higher frequency to have better performance. Lower input voltage usually comes from a battery, so the RT6576F operates with lower switching frequency for lower switching losses. For a specific input voltage range, the switching cycle period is given by :

For 5V V<sub>OUT</sub>,

$$\text{Period (sec.)} = \frac{V_{IN} \times 2.7 \times 10^{-6}}{V_{IN} - 3.79}$$

For 3.3V V<sub>OUT</sub>,

$$\text{Period (sec.)} = \frac{V_{IN} \times 2.45 \times 10^{-6}}{V_{IN} - 2.59}$$

where the V<sub>IN</sub> is in volt.

The on-time guaranteed in the Electrical Characteristics table is influenced by switching delays in the external high-side power MOSFET.

### Diode Emulation Mode

In diode emulation mode, the RT6576F automatically reduces switching frequency at light load conditions to maintain high efficiency. This reduction of frequency is achieved smoothly. As the output current decreases from heavy load condition, the inductor current is also reduced, and eventually comes to the point that its current valley touches zero, which is the boundary between continuous conduction and discontinuous conduction modes. To emulate the behavior of diodes, the low-side MOSFET allows only partial negative current to flow when the inductor free wheeling current becomes negative. As the load current is further decreased, it takes longer and longer

time to discharge the output capacitor to the level that requires the next “ON” cycle. The on-time is kept the same as that in the heavy load condition. In reverse, when the output current increases from light load to heavy load, the switching frequency increases to the preset value as the inductor current reaches the continuous conduction. The transition load point to the light load operation is shown in Figure 1. and can be calculated as follows :

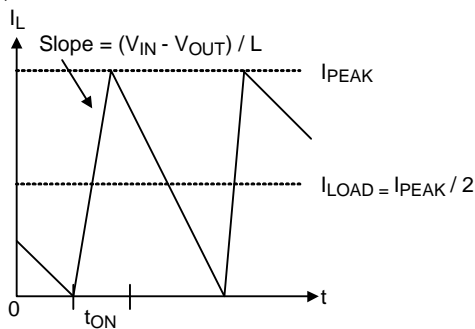


Figure 1. Boundary Condition of CCM/DEM

$$I_{LOAD(SKIP)} \approx \frac{(V_{IN} - V_{OUT})}{2L} \times t_{ON}$$

where  $t_{ON}$  is the on-time.

The switching waveforms may appear noisy and asynchronous when light load causes diode emulation operation. This is normal and results in high efficiency. Trade offs in PFM noise vs. light load efficiency is made by varying the inductor value. Generally, low inductor values produce a broader efficiency vs. load curve, while higher values result in higher full load efficiency (assuming that the coil resistance remains fixed) and less output voltage ripple. Penalties for using higher inductor values include larger physical size and degraded load transient response (especially at low input voltage levels).

### Ultrasonic Mode (ASM)

The RT6576F activates a unique type of diode emulation mode with a minimum switching frequency of 25kHz, called ultrasonic mode. This mode eliminates audio-frequency modulation that would otherwise be present when a lightly loaded controller automatically skips pulses. In ultrasonic mode, the low-side switch gate driver signal is “OR”ed with an internal oscillator (>25kHz). Once the internal oscillator is triggered, the controller will turn on UGATE and give it shorter on-time.

When the on-time expired, LGATE turns on until the inductor current goes to zero crossing threshold and keep both high-side and low-side MOSFET off to wait for the next trigger. Because shorter on-time causes a smaller pulse of the inductor current, the controller can keep output voltage and switching frequency simultaneously. The on-time decreasing has a limitation and the output voltage will be lifted up under the slight load condition. The controller will turn on LGATE first to pull down the output voltage. When the output voltage is pulled down to the balance point of the output load current, the controller will proceed the short on-time sequence as the above description.

### Linear Regulators (LDOx)

The RT6576F includes 5V (LDO5) and 3.3V (LDO3) linear regulators. The regulators can supply up to 100mA for external loads. Bypass LDOx with a 1μF to 4.7μF, and recommended value is 1μF ceramic capacitor. When  $V_{OUT1}$  is higher than the switch over threshold (4.66V), an internal 1.5Ω P-MOSFET switch connects BYP1 to the LDO5 pin while simultaneously disconnects the internal linear regulator.

### Current Limit Setting

The RT6576F has cycle-by-cycle current limit control. The current limit circuit employs an unique “valley” current sensing algorithm. If the magnitude of the current sense signal at PHASEx is above the current limit threshold, the PWM is not allowed to initiate a new cycle (Figure 2). The actual peak current is greater than the current limit threshold by an amount equal to the inductor ripple current. Therefore, the exact current limit characteristic and maximum load capability are a function of the sense resistance, inductor value, battery and output voltage.

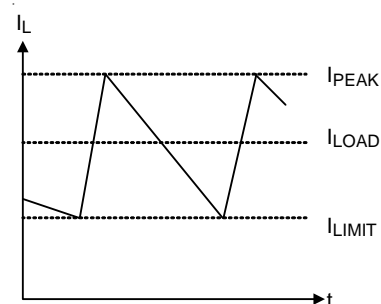


Figure 2. “Valley” Current Limit

The RT6576F uses the on resistance of the synchronous rectifier as the current sense element and supports temperature compensated MOSFET  $R_{DS(ON)}$  sensing. The  $R_{ILIM}$  resistor between the CSx pin and GND sets the current limit threshold. The resistor  $R_{ILIM}$  is connected to a current source from CSx which is  $10\mu A$  (typ.) at room temperature. The current source has a  $4700ppm/^{\circ}C$  temperature slope to compensate the temperature dependency of the  $R_{DS(ON)}$ . When the voltage drop across the sense resistor or low-side MOSFET equals  $1/8$  the voltage across the  $R_{ILIM}$  resistor, positive current limit will be activated. The high-side MOSFET will not be turned on until the voltage drop across the MOSFET falls below  $1/8$  the voltage across the  $R_{ILIM}$  resistor.

Choose a current limit resistor according to the following equation :

$$V_{LIMIT} = (R_{LIMIT} \times 10\mu A - 35mV) / 8 = I_{LIMIT} \times R_{DS(ON)}$$

$$R_{LIMIT} = ((I_{LIMIT} \times R_{DS(ON)}) \times 8 + 35mV) / 10\mu A$$

Carefully observe the PC board layout guidelines to ensure that noise and DC errors do not corrupt the current sense signal at PHASEx and GND. Mount or place the IC close to the low-side MOSFET.

**VCLK for Charge Pump**

A 260kHz VCLK signal can be used for the external charge pump circuit. The VCLK signal becomes available when EN1 enters ON state. VCLK driver circuit is driven by BYP1 voltage.

The external 14V charge pump is driven by VCLK. As shown in Figure 3, when VCLK is low, C1 will be charged by  $V_{OUT1}$  through D1. C1 voltage is equal to  $V_{OUT1}$  minus the diode drop. When VCLK becomes high, C1 transfers the charge to C2 through D2 and charges C2 voltage to  $V_{VCLK}$  plus C1 voltage. As VCLK transitions low on the next cycle, C3 is charged to C2 voltage minus a diode drop through D3. Finally, C3 charges C4 through D4 when VCLK switches high. Thus, the total charge pump voltage,  $V_{CP}$ , is :

$$V_{CP} = V_{OUT1} + 2 \times V_{VCLK} - 4 \times V_D$$

where  $V_{VCLK}$  is the peak voltage of the VCLK driver which is equal to LDO5 and  $V_D$  is the forward voltage dropped across the Schottky diode.

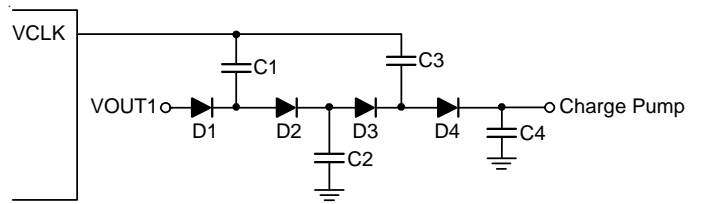


Figure 3. Charge Pump Circuit Connected to VCLK

**MOSFET Gate Driver (UGATEx, LGATEx)**

The high-side driver is designed to drive high current, low  $R_{DS(ON)}$  N-MOSFET(s). When configured as a floating driver, 5V bias voltage is delivered from the LDO5 supply. The average drive current is also calculated by the gate charge at  $V_{GS} = 5V$  times switching frequency. The instantaneous drive current is supplied by the flying capacitor between the BOOTx and PHASEx pins. A dead-time to prevent shoot through is internally generated from high-side MOSFET off to low-side MOSFET on and low-side MOSFET off to high-side MOSFET on.

The low-side driver is designed to drive high current low  $R_{DS(ON)}$  N-MOSFET(s). The internal pull down transistor that drives LGATEx low is robust, with a  $1\Omega$  typical on-resistance. A 5V bias voltage is delivered from the LDO5 supply. The instantaneous drive current is supplied by an input capacitor connected between LDO5 and GND.

For high current applications, some combinations of high and low-side MOSFETs may cause excessive gate drain coupling, which leads to efficiency killing, EMI producing, and shoot through currents. This is often remedied by adding a resistor in series with BOOTx, which increases the turn-on time of the high-side MOSFET without degrading the turn-off time. See Figure 4.

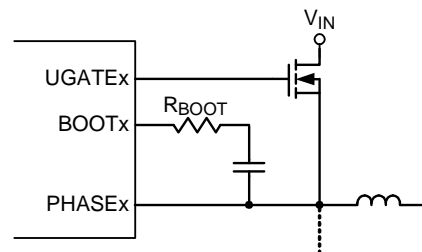


Figure 4. Increasing the UGATEx Rise Time

### Soft-Start

The RT6576F provides an internal soft-start function to prevent large inrush current and output voltage overshoot when the converter starts up. The soft-start (SS) automatically begins once the chip is enabled. During soft-start, it clamps the ramping of internal reference voltage which is compared with FBx signal. The minimum soft-start duration is 2ms. A unique PWM duty limit control that prevents output over-voltage during soft-start period is designed specifically for FBx floating.

### UVLO Protection

The RT6576F has LDO5 under-voltage lock out protection (UVLO). When the LDO5 voltage is lower than 3.9V (typ.) and the LDO3 voltage is lower than 2.5V (typ.), both switch power supplies are shut off. This is a non-latch protection.

### Power Good Output (PGOOD)

PGOOD is an open-drain output and requires a pull-up resistor. PGOOD is actively held low in soft-start, standby, and shutdown. For the RT6576F, PGOOD is released when both output voltages are above 88% of nominal regulation point. The PGOOD signal goes low if either output turns off or is 20% below or 13% over its nominal regulation point.

### Output Over-Voltage Protection (OVP)

The output voltage can be continuously monitored for over-voltage condition. If the output voltage exceeds 13% of its set voltage threshold, the over-voltage protection is triggered and the LGATEx low-side gate drivers are forced high. This activates the low-side MOSFET switch, which rapidly discharges the output capacitor and pulls the output voltage downward.

The RT6576F is latched once OVP is triggered and can only be released by either toggling ENx or cycling VIN. There is a 1 $\mu$ s delay built into the over-voltage protection circuit to prevent false transition.

Note that latching LGATEx high will cause the output voltage to dip slightly negative due to previously stored energy in the LC tank circuit. For loads that cannot tolerate a negative voltage, place a power Schottky diode across the output to act as a reverse polarity clamp.

If the over-voltage condition is caused by a shorted in high-side switch, turning the low-side MOSFET on 100% will create an electrical shorted circuit between the battery and GND to blow the fuse and disconnecting the battery from the output.

### Output Under-Voltage Protection (UVP)

The output voltage can be continuously monitored for under-voltage condition. If the output is less than 52% (typ.) of its set voltage threshold, the under-voltage protection will be triggered and then both UGATEx and LGATEx gate drivers will be forced low. The UVP is ignored for at least 4.5ms (typ.) after a start-up or a rising edge on ENx. Toggle ENx or cycle VIN to reset the UVP fault latch and restart the controller.

### Thermal Protection

The RT6576F features thermal shutdown to prevent damage from excessive heat dissipation. Thermal shutdown occurs when the die temperature exceeds 150°C. All internal circuitries are turned off during thermal shutdown. The RT6576F triggers thermal shutdown if LDO5 is not supplied from V<sub>OUT1</sub>, while input voltage on VIN and drawing current from LDO5 are too high. Nevertheless, even if LDO5 is supplied from V<sub>OUT1</sub>, overloading LDO5 can cause large power dissipation on automatic switches, which may still result in thermal shutdown.

### Discharge Mode (Soft Discharge)

When ENx is low the output under-voltage fault latch is set, the output discharge mode will be triggered. During discharge mode, an internal switch creates a path for discharging the output capacitors' residual charge to GND.

### Standby Mode

When VIN exceeds POR threshold and ENx < 0.4V, the RT6576F operate in standby mode, and CH1 and CH2 are OFF state. For the RT6576F, LDO5 and LDO3 are ON state and approximately consumes 25 $\mu$ A while in standby mode.

### Power-Up Sequencing and On/Off Controls (ENx)

EN1 and EN2 control the power-up sequencing of the two channels of the Buck converter. The 0.4V falling edge threshold on ENx can be used to detect a specific analog



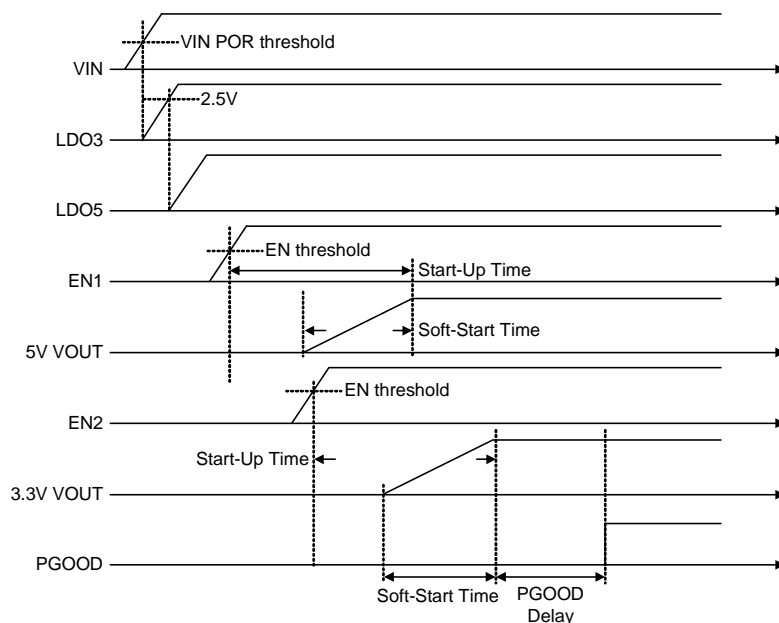
voltage level and to shutdown the device. Once in shutdown, the 1.6V rising edge threshold activates, providing sufficient hysteresis for most applications.

**Table 1. Operation Mode Truth Table**

Mode	Condition	Comment
<b>LDO Over Current Limit</b>	LDOx < UVLO threshold	Transitions to discharge mode after VIN POR. LDO5 and LDO3 remain active.
<b>Run</b>	ENx = high, V <sub>OUT1</sub> or V <sub>OUT2</sub> are enabled	Normal Operation.
<b>Over-Voltage Protection</b>	Either output >113% of the nominal level.	LGATEx is forced high. LDO3 and LDO5 are active. Exit by VIN POR or by toggling ENx.
<b>Under-Voltage Protection</b>	Either output < 52% of the nominal level after 1.3ms time-out expires and output is enabled	Both UGATEx and LGATEx are forced low and enter discharge mode. LDO3 and LDO5 are active. Exit by VIN POR or by toggling ENx.
<b>Discharge</b>	Either output is still high in standby mode	During discharge mode, there is one path to discharge the output capacitors' residual charge to GND via an internal switch.
<b>Standby</b>	VIN > POR ENx < 0.4V	LDO3, LDO5 are active
<b>Thermal Shutdown</b>	T <sub>J</sub> > 150°C	All circuitries are off. Exit by VIN POR.

**Table 2. Enabling/PGOOD State**

EN1	EN2	LDO5	LDO3	CH1 (5VOUT)	CH2 (3.3VOUT)	VCLK	PGOOD
OFF	OFF	ON	ON	OFF	OFF	OFF	Low
ON	OFF	ON	ON	ON	OFF	ON	Low
OFF	ON	ON	ON	OFF	ON	OFF	Low
ON	ON	ON	ON	ON	ON	ON	High



**Figure 5. Timing Diagram**

### Output Voltage Setting (FBx)

Connect a resistive voltage divider at the FBx pin between  $V_{OUTx}$  and GND to adjust the output voltage from 2V to 5.5V for CH1 and 2V to 4V for CH2, as shown in Figure 6. The recommended R2 value is between 10kΩ to 20kΩ, and solve for R1 using the equation below :

$$V_{OUT(Valley)} = V_{FBx} \times \left( 1 + \left( \frac{R1}{R2} \right) \right)$$

where  $V_{FBx}$  is 2V (typ.).

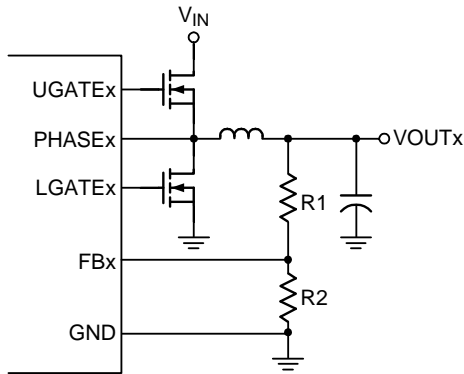


Figure 6. Setting  $V_{OUTx}$  with a Resistive Voltage Divider

### Output Inductor Selection

The switching frequency (on-time) and operating point (% ripple or LIR) determine the inductor value as shown below :

$$L = \frac{t_{ON} \times (V_{IN} - V_{OUTx})}{LIR \times I_{LOAD(MAX)}}$$

where LIR is the ratio of the peak-to-peak ripple current to the average inductor current.

Find a low-loss inductor having the lowest possible DC resistance that fits in the allotted dimensions. Ferrite cores are often the best choice, although powdered iron is inexpensive and can work well at 200kHz. The core must be large enough not to saturate at the peak inductor current,  $I_{PEAK}$ :

$$I_{PEAK} = I_{LOAD(MAX)} + \left[ \left( LIR / 2 \right) \times I_{LOAD(MAX)} \right]$$

The calculation above shall serve as a general reference. To further improve transient response, the output inductance can be further reduced. Of course, besides the inductor, the output capacitor should also be considered when improving transient response.

### Output Capacitor Selection

The capacitor value and ESR determine the amount of output voltage ripple and load transient response. Thus, the capacitor value must be greater than the largest value calculated from the equations below :

$$V_{SAG} = \frac{(\Delta I_{LOAD})^2 \times L \times (t_{ON} + t_{OFF\_MIN})}{2 \times C_{OUT} \times [V_{IN} \times t_{ON} - V_{OUTx} (t_{ON} + t_{OFF\_MIN})]}$$

$$V_{SOAR} = \frac{(\Delta I_{LOAD})^2 \times L}{2 \times C_{OUT} \times V_{OUTx}}$$

$$V_{P-P} = LIR \times I_{LOAD(MAX)} \times \left( ESR + \frac{1}{8 \times C_{OUT} \times f} \right)$$

where  $V_{SAG}$  and  $V_{SOAR}$  are the allowable amount of undershoot and overshoot voltage during load transient,  $V_{P-P}$  is the output ripple voltage, and  $t_{OFF(MIN)}$  is the minimum off-time.

### Thermal Considerations

The junction temperature should never exceed the absolute maximum junction temperature  $T_{J(MAX)}$ , listed under Absolute Maximum Ratings, to avoid permanent damage to the device. The maximum allowable power dissipation depends on the thermal resistance of the IC package, the PCB layout, the rate of surrounding airflow, and the difference between the junction and ambient temperatures. The maximum power dissipation can be calculated using the following formula :

$$P_{D(MAX)} = (T_{J(MAX)} - T_A) / \theta_{JA}$$

where  $T_{J(MAX)}$  is the maximum junction temperature,  $T_A$  is the ambient temperature, and  $\theta_{JA}$  is the junction-to-ambient thermal resistance.

For continuous operation, the maximum operating junction temperature indicated under Recommended Operating Conditions is 125°C. The junction-to-ambient thermal resistance,  $\theta_{JA}$ , is highly package dependent. For a WQFN-20L 3x3 package, the thermal resistance,  $\theta_{JA}$ , is 30°C/W on a standard JEDEC 51-7 high effective-thermal-conductivity four-layer test board. The maximum power dissipation at  $T_A = 25^\circ\text{C}$  can be calculated as below :

$P_{D(MAX)} = (125^{\circ}\text{C} - 25^{\circ}\text{C}) / (30^{\circ}\text{C}/\text{W}) = 3.33\text{W}$  for a WQFN-20L 3x3 package.

The maximum power dissipation depends on the operating ambient temperature for the fixed  $T_{J(MAX)}$  and the thermal resistance,  $\theta_{JA}$ . The derating curves in Figure 7 allows the designer to see the effect of rising ambient temperature on the maximum power dissipation.

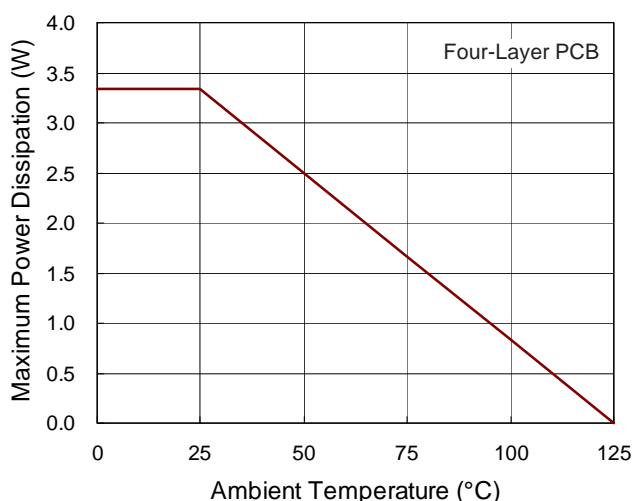


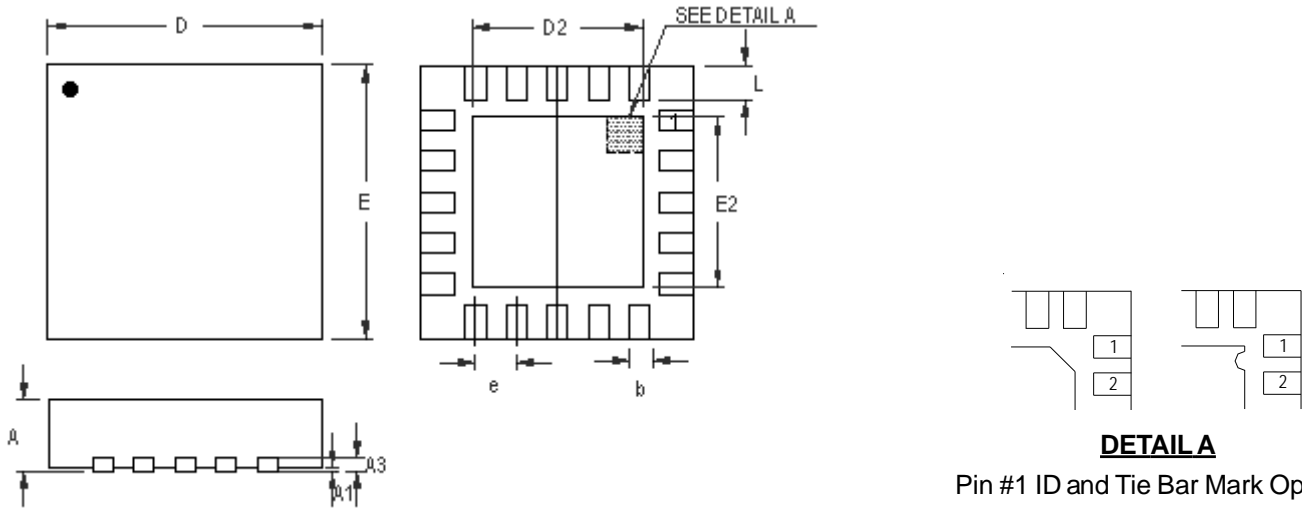
Figure 7. Derating Curve of Maximum Power Dissipation

**Layout Considerations**

Layout is very important in high frequency switching converter design. Improper PCB layout can radiate excessive noise and contribute to the converter’s instability. Certain points must be considered before starting a layout with the RT6576F.

- ▶ Place the filter capacitor close to the IC, within 12mm (0.5 inch) if possible.
- ▶ Keep current limit setting network as close as possible to the IC. Routing of the network should avoid coupling to high-voltage switching node.
- ▶ Connections from the drivers to the respective gate of the high-side or the low-side MOSFET should be as short as possible to reduce stray inductance. Use 0.65mm (25 mils) or wider trace.
- ▶ All sensitive analog traces and components such as FBx, PGOOD, and should be placed away from high voltage switching nodes such as PHASEx, LGATEx, UGATEx, or BOOTx nodes to avoid coupling. Use internal layer(s) as ground plane(s) and shield the feedback trace from power traces and components.
- ▶ Place ground terminal of VIN capacitor(s), VOUTx capacitor(s), and Source of low-side MOSFETs as close to each other as possible. The PCB trace of PHASEx node, which connects to Source of high-side MOSFET, Drain of low-side MOSFET and high voltage side of the inductor, should be as short and wide as possible.

## Outline Dimension

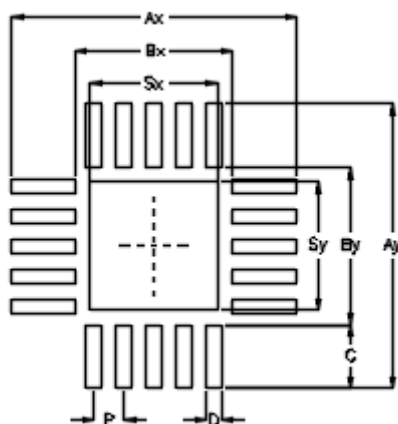


Note : The configuration of the Pin #1 identifier is optional, but must be located within the zone indicated.

Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
A	0.700	0.800	0.028	0.031
A1	0.000	0.050	0.000	0.002
A3	0.175	0.250	0.007	0.010
b	0.150	0.250	0.006	0.010
D	2.900	3.100	0.114	0.122
D2	1.650	1.750	0.065	0.069
E	2.900	3.100	0.114	0.122
E2	1.650	1.750	0.065	0.069
e	0.400		0.016	
L	0.350	0.450	0.014	0.018

### W-Type 20L QFN 3x3 Package

**Footprint Information**



Package	Number of Pin	Footprint Dimension (mm)									Tolerance
		P	Ax	Ay	Bx	By	C	D	Sx	Sy	
V/W/U/XQFN3*3-20	20	0.40	3.80	3.80	2.10	2.10	0.85	0.20	1.70	1.70	±0.05

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